

# Uncovering the Costs of High Inflation

Ken Miyahara



Alberto Cavallo



Francesco Lippi

University of Chicago

Harvard Business School

LUISS & EIEF

NBER Summer Institute, July 10, 2025

## Motivation for Geeks :-)

let  $x \equiv \log(p/p^*)$  be price gap,  $\mu$  be inflation

In NK models cost of inflation shows up in:  $\chi \propto \text{Var}(x)$ ; study  $\frac{\partial \log \chi}{\partial \log \mu}$

Economist observes distribution  $\Delta x$  but not of  $x$ ; need a model to connect the two

## Motivation for Geeks :-)

let  $x \equiv \log(p/p^*)$  be price gap,  $\mu$  be inflation

In NK models cost of inflation shows up in:  $\chi \propto \text{Var}(x)$ ; study  $\frac{\partial \log \chi}{\partial \log \mu}$

Economist observes distribution  $\Delta x$  but not of  $x$ ; need a model to connect the two

Cost of inflation varies a lot across models (examples)

	Calvo model	Sheshinsky-Weiss	Golosov-Lucas
		$\sigma^2/\mu \rightarrow 0$	$\sigma^2/\mu \rightarrow \infty$
$\frac{\partial \log \chi(\mu)}{\partial \log \mu} \approx$	2	2/3	$\approx 0$ at small $\mu$

Match with data selects model with "reasonable"  $\sigma^2/\mu$

# This paper: welfare costs of inflation from a NK perspective

Costs: “inefficient price dispersion” and wasteful “price setting activities”

- ▶ Today: add an information friction to a canonical sticky price model
  - firms engage in **info-collection** (research) and **price adjustment** activities
- ▶ In the model higher inflation leads firms to
  - pay less attention to own idiosyncratic info (wider inaction region, a “SW effect”)
  - choose more dispersed markups (new channel for price dispersion)
- ▶ Calibrate model using granular data from Turkey (moderate to high inflation)
  - analyze an episode where inflation tripled
  - costs of inflation not so elusive, steep inflation gradient

## Related NK literature

- ▶ empirical: Nakamura et al (QJE18) “Elusive cost of inflation”, ongoing work by Adam-Alexandrov-Weber
- ▶ modeling sticky price w. inattention  
Mackowiack-Wiederholt (AER09), Alvarez-Lippi-Paciello (QJE11)
- ▶ Inverse inference problem: recovering distr.  $x$  from  $\Delta x$   
Alvarez-Lippi-Oskolkov (QJE 22), Bailey-Blanco (RES 23)
- ▶ menu cost model for high inflation countries  
Gagnon (QJE09), Alvarez-Beraja-Neumeyer et al (QJE19)
- ▶ “rockets and feathers” w asymmetric profit function  
Fernandez-Villaverde et al (AER15), Cavallo-Lippi-Miyahara (AER124)

# Simple Model of Demand and Production

- ▶ Monopolistic competition with CES demand  $A_i c_i = \left( \frac{p_i / A_i}{P} \right)^\eta C$
- ▶ Production: CRS in labor  $y_i = h_i / Z_i$  where  $Z_i = \exp(\underbrace{z_i}_{\text{STD } \sigma})$
- ▶ Definition: **Price gap**  $x_i \equiv \log p_i - \log \underbrace{\frac{\eta}{\eta - 1} Z_i W}_{\equiv p_i^*}$
- ▶ constant money growth  $\mu$  and  $A_i = Z_i$  keeps math simple
- ▶ gap's law of motion:  $dx = -\mu dt + \sigma dZ_i$
- ▶ No complementarities between firms' decisions & steady state analysis

# The Firm's price setting problem

- ▶ Firm knows inflation  $\mu$  but does not know marginal costs  $Z_i$   
Price-setting requires costly communication with production plant
- ▶ Info discoveries (about  $Z_i$ ) arrive at chosen hazard:  $\omega$
- ▶ Price adjustment opportunities arrive at chosen hazard:  $\alpha$
- ▶ uncontrolled evolution of expected gap  $\bar{x}(t) \equiv \mathbb{E}(x(t))$ , for firm with  $t_0$  info

$$\bar{x}(t) = x(t_0) - \mu \cdot (t - t_0) \quad , \quad \tau(t) \equiv t - t_0 \quad , \quad x(t) \sim \mathcal{N}(\bar{x}(t), \sigma^2 \tau(t))$$

- ▶ The firm's **state**:  $\{\bar{x}, \tau\}$  is the *predicted gap* and the *information age*

# The Firm's problem

- ▶ Flow cost  $F(x)$ : forgone profits (w. CES demand system) due to  $x \neq 0$
- ▶ Firm's value function solves

$$\begin{aligned} v(\bar{x}(\tau), \tau) = & \min_{\alpha, \omega} \mathbb{E} \left( \int_0^{\min \{ \tau^a, \tau^r \}} e^{-\rho s} [F(x(\tau + s)) + \kappa_a \alpha(s)^2 + \kappa_r \omega(s)^2] ds \right. \\ & + \mathbf{1}^a \cdot e^{-\rho \tau^a} \min_{x^*} v(x^*, \tau + \tau^a) \\ & \left. + (1 - \mathbf{1}^a) \cdot e^{-\rho \tau^r} v(x(\tau + \tau^r), 0) \mid \bar{x}(\tau), \tau \right) \end{aligned}$$

- ▶ indicator function  $\mathbf{1}^a$  equals 0 if new info arrives before adjustment



# The Firm's problem (in recursive form)

- ▶ Firm's value function  $v$  solves HJB: appdx: derivation from sequence prob

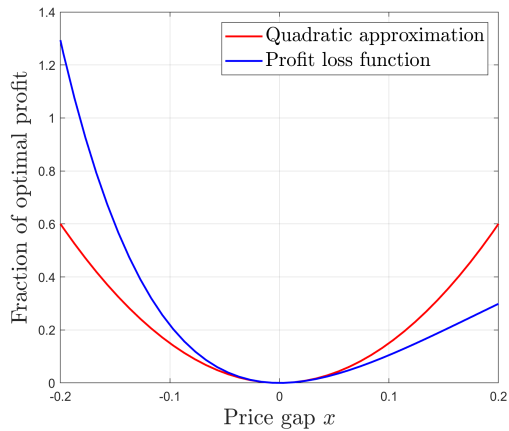
$$\begin{aligned}\rho v(\bar{x}, \tau) = & \mathbb{E}[F(x)|\bar{x}, \tau] - \mu \partial_{\bar{x}} v(\bar{x}, \tau) + \partial_{\tau} v(\bar{x}, \tau) \\ & + \min_{\alpha \geq 0, \bar{x}^*} \{ \alpha \cdot [v(\bar{x}^*, \tau) - v(\bar{x}, \tau)] + \kappa_a \alpha^2 \} \\ & + \min_{\omega \geq 0} \{ \omega \cdot [\mathbb{E}[v(x, 0)|\bar{x}, \tau] - v(\bar{x}, \tau)] + \kappa_r \omega^2 \}\end{aligned}$$

- ▶  $\mathbb{E}$  with respect to  $\mathcal{N}(\bar{x}, \sigma^2 \tau)$ , where  $\bar{x}(t) = x(t_0) - \mu \cdot (t - t_0)$  ,  $\tau(t) = t - t_0$

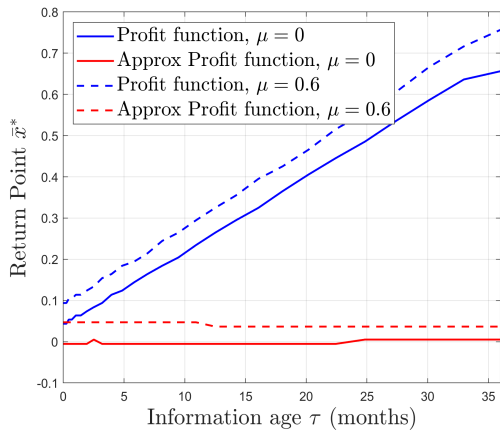
$\implies$  Policy: Hazard functions  $\alpha(\bar{x}, \tau)$  ,  $\omega(\bar{x}, \tau)$  and return point  $\bar{x}^*(\tau)$

# Forgone Profits and Optimal Return Point

(a) Forgone Profit Function  $F(x)$



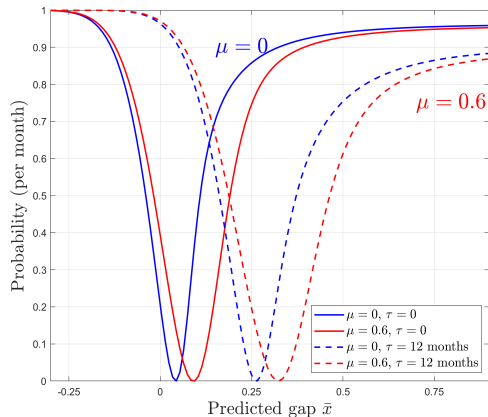
(b) Return points  $\bar{x}^*(\tau)$  for  $\mu \in \{0, 0.6\}$



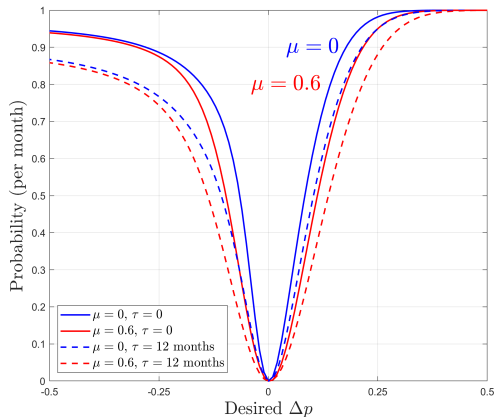
– *hedging motive* as information ages (high  $\tau$ , as in Fernandez-Villaverde et al paper)

# Adjustment Hazard

(a) Hazard of adjustment (uncentered)  
 $\alpha(\bar{X}, \tau; \mu)$



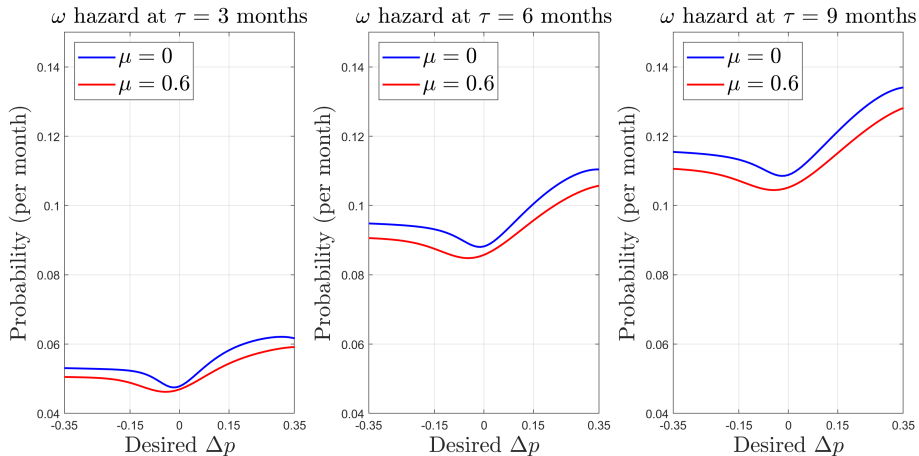
(b) Hazard of adjustment (centered)  
 $\alpha(\bar{X}^*(\tau) - \Delta p, \tau; \mu)$



– *wider inaction* as information ages (reduces the importance of idiosyncratic shocks )

# Research Hazard

Research hazard  $\omega(\bar{x}^*(\tau) - \Delta p, \tau; \mu)$



– Large gradient w.r.t.  $\tau$ , small gradient w.r.t  $\mu$

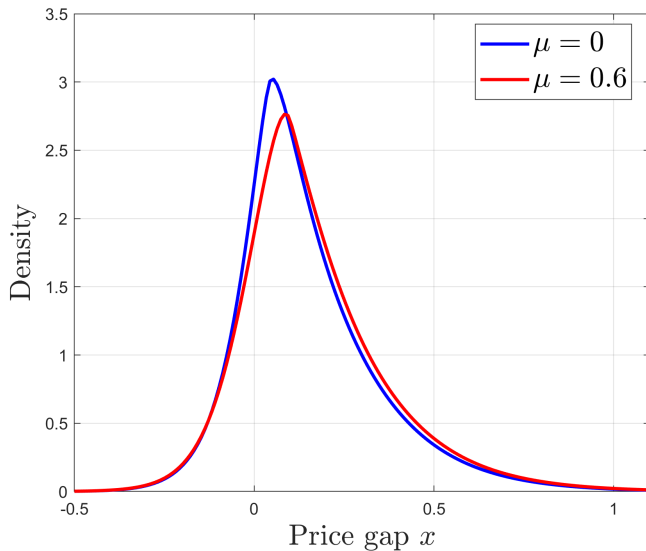
# Cross-section aggregation of firms

- ▶ Aggregation: Kolmogorov equation  $\bar{m}(\bar{x}, \tau)$  (omit arguments)

$$(\alpha + \omega) \bar{m} = \mu \partial_{\bar{x}} \bar{m} - \partial_{\tau} \bar{m}$$

- ▶ using  $x \sim \mathcal{N}(\bar{x}, \sigma^2 \tau)$  gives distribution of actual gaps and info age  $m(x, \tau)$

## Aggregation: Marginal distribution of $x$



# Mapping Model to Observables

- Frequency of price adjustment and research

$$N_a = \int_0^\infty \int_{-\infty}^\infty \alpha(\bar{x}, \tau) \cdot \bar{m}(\bar{x}, \tau) d\bar{x} d\tau$$

$$N_r = \int_0^\infty \int_{-\infty}^\infty \omega(\bar{x}, \tau) \cdot \bar{m}(\bar{x}, \tau) d\bar{x} d\tau$$

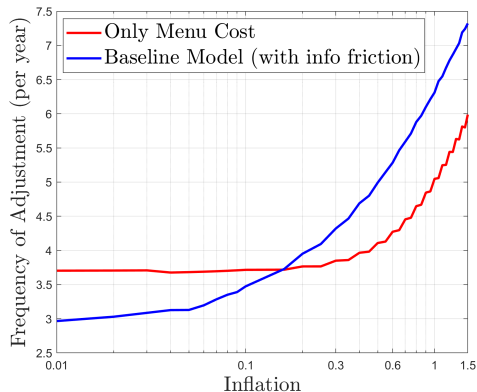
- Distribution of price changes

$$q(\Delta p) = \int_0^\infty \int_{-\infty}^\infty \mathbb{1}(\bar{x}, \tau; \Delta p) \cdot \alpha(\bar{x}, \tau) \cdot \bar{m}(\bar{x}, \tau) d\bar{x} d\tau$$

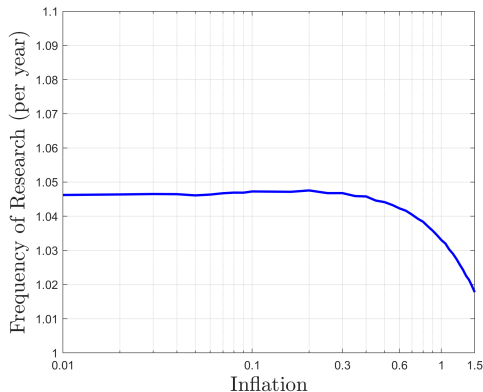
where  $\mathbb{1}(\bar{x}, \tau; \Delta p) \equiv \{(\bar{x}, \tau) : \bar{x}^*(\tau) - \bar{x} = \Delta p\}$

# Adjustment and Research frequency wrt inflation

(a) Adjustment Frequency  $N_a$



(b) Research frequency  $N_r$



– menu cost flat because  $\sigma/\mu$  large; info friction make model more SW like



## What's in a price change: $\Delta p$ ?

- Firm with  $(\bar{x}^*(\tau_0), \tau_0)$  chooses  $\Delta p$  after **spell of duration**  $\tau^a$
- **Information age** at adjustment:  $\tau \in [0, \tau_0 + \tau^a]$

► Then  $\Delta p$  related to  $(\tau^a, \tau)$  as follows:

$$\Delta p = \underbrace{\bar{x}^*(\tau) - \bar{x}^*(\tau_0)}_{\text{info age difference}} + \underbrace{\mu \tau^a}_{\text{keep up with } \mu} - \underbrace{\sigma Z(\tau_0 + \tau^a - \tau)}_{\text{new info}}$$

where  $Z$  is a Wiener process with  $Z(0) = 0$ . [Details](#)

## What's in a price change: $\Delta p$ ?

- Firm with  $(\bar{x}^*(\tau_0), \tau_0)$  chooses  $\Delta p$  after **spell of duration**  $\tau^a$
- **Information age** at adjustment:  $\tau \in [0, \tau_0 + \tau^a]$

► Then  $\Delta p$  related to  $(\tau^a, \tau)$  as follows:

$$\Delta p = \underbrace{\bar{x}^*(\tau) - \bar{x}^*(\tau_0)}_{\text{info age difference}} + \underbrace{\mu \tau^a}_{\text{keep up with } \mu} - \underbrace{\sigma Z(\tau_0 + \tau^a - \tau)}_{\text{new info}}$$

where  $Z$  is a Wiener process with  $Z(0) = 0$ . [Details](#)

► We get:  $N_a \tilde{E} (\Delta p - \mu \tau^a)^2 = N_a \widetilde{\text{Var}}(\bar{x}^*(\tau) - \bar{x}^*(\tau_0)) + \sigma^2$

# Costs of inflation in the theoretical model

- ▶ Misallocation,  $\chi$ , due to price gaps

$$\text{Misall. Cost}_\mu = \frac{\eta}{2} \text{Var}_\mu(x)$$

- ▶ Price management,  $\phi$ , of adjustment and research

$$\text{Mgmt. Cost}_\mu = \frac{1}{\eta} E_\mu [\kappa_a(\alpha(\bar{X}, \tau))^2 + \kappa_r(\omega(\bar{X}, \tau))^2]$$

- ▶ Costs of inflation are defined in excess of levels at  $\mu = 0$

$$\chi(\mu) = \text{Misall. Cost}_\mu - \text{Misall. Cost}_0, \quad \phi(\mu) = \text{Mgmt. Cost}_\mu - \text{Mgmt. Cost}_0$$

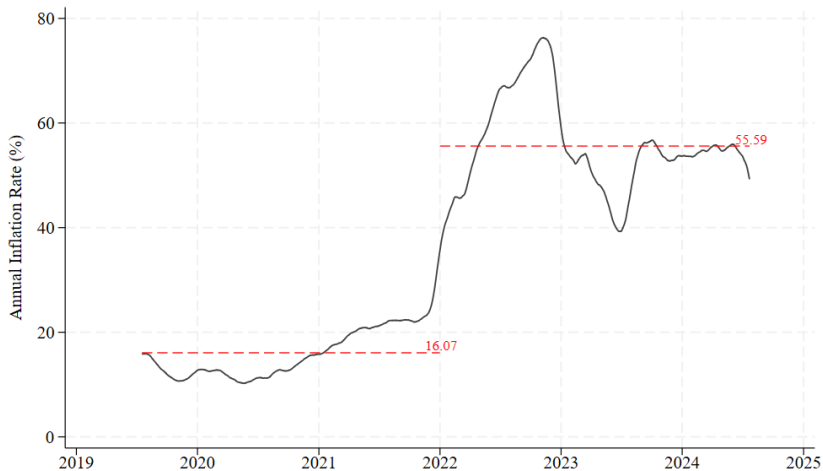
## A simple exercise

- ▶ Calibrate model to Turkey with “moderate” to “high” inflation periods
- ▶ Analyze “misallocation” and “price management” costs as fct. of inflation

# Data

- ▶ PriceStats data (Cavallo and Rigobon, 2016)
- ▶ Micro-data: Food and beverages sectors in Turkey (14 largest retailers)
- ▶ Sample period between June 2019 and July 2024
- ▶ Price changes and duration of completed price spells at daily frequency

# Turkey: Inflation time series (source Pricestats)

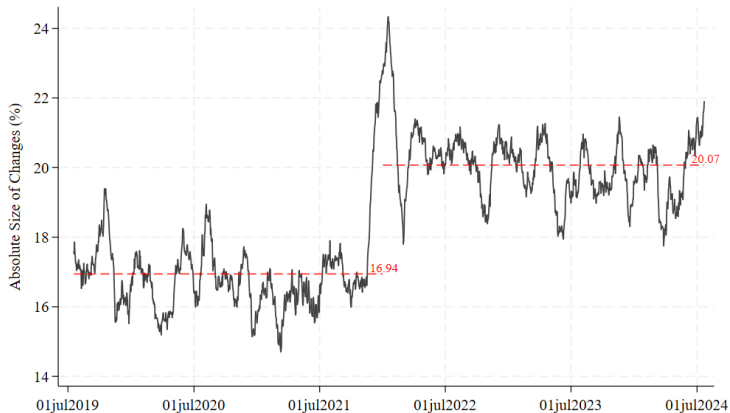


# Turkey: Frequency of price adjustment



$$\text{elasticity } \theta \equiv \frac{\partial \log N}{\partial \log \mu} = 0.6$$

# Turkey: Absolute Size of Price Changes



This moment is Nakamura et. al (2018) measure for the cost of inflation.

Our calibration yields a similar non-targeted increase around 20% (from 13% to 16%)



# Calibration

- ▶ select four parameters:  $\{\mu, \sigma^2, \kappa_a, \kappa_r\}$
- ▶ to match four moments:  $\{\tilde{E}(\Delta p), N_a, \tilde{E}(\Delta p - \mu\tau^a)^2, \frac{\Delta \log N_a}{\Delta \log \mu}\}$

Useful model identities (blue is data) :

$$N_a \tilde{E}(\Delta p - \mu\tau^a)^2 = N_a \underbrace{\widetilde{\text{Var}}(\bar{x}^*(\tau) - \bar{x}^*(\tau_0))}_{\text{Information dispersion}} + \sigma^2$$

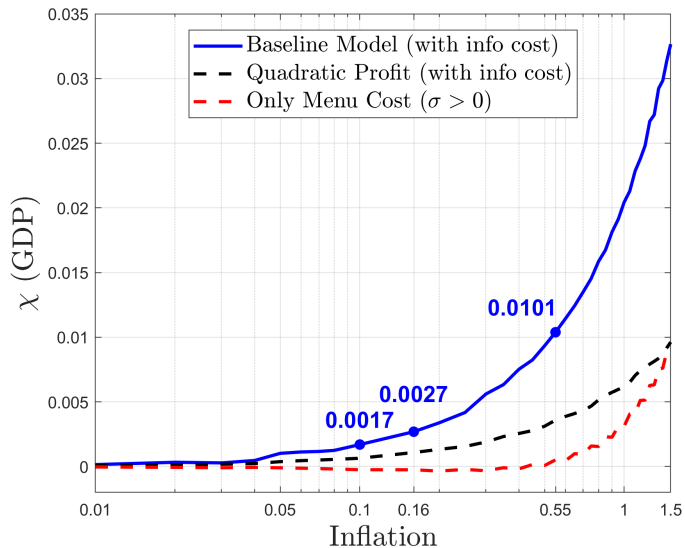
$$\frac{1}{\tilde{E}\tau^a} = N_a, \quad N_a \tilde{E}(\Delta p) = \mu, \quad \text{also } \theta \equiv \frac{\Delta \log N_a}{\Delta \log \mu} \text{ is increasing in } \frac{\mu}{\sigma^2}$$

## Calibration for Turkey for 2019-2021 (inflation is $\mu = 0.16$ )

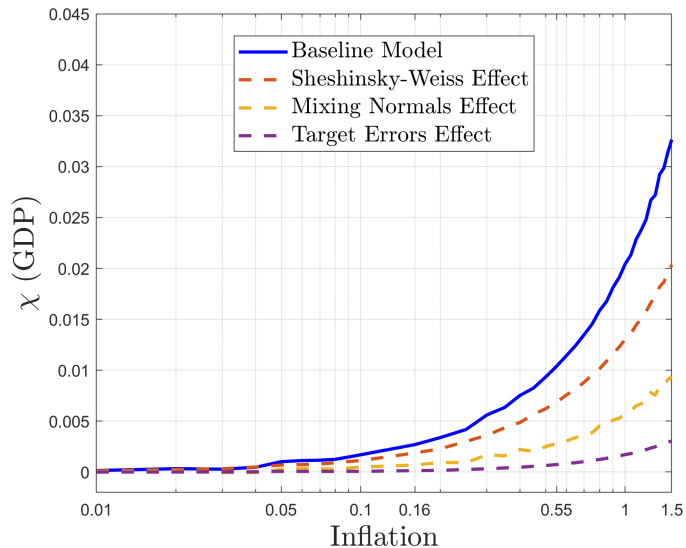
	Targeted moments				Parameters				Others
	$N_a$	$E[\Delta p]$	$N_a \tilde{E}[(\Delta p - \mu_{\tau^a})^2]$	Elasticity $\theta$	$\sigma^2$	$\kappa_a$	$\kappa_r$	$\mu$	$N_r$
data	3.7	0.04	0.10	0.57	—	—	—	—	—
W. info frictions	3.7	0.04	0.10	0.37	0.04	$0.025^2$	$0.25^2$	0.16	1
W/o info frictions	3.7	0.04	0.10	0.11	0.10	$0.037^2$	—	0.16	—

- model with info friction better at capturing extensive margin response
- w/o info friction high inflation requires larger variance of marginal costs

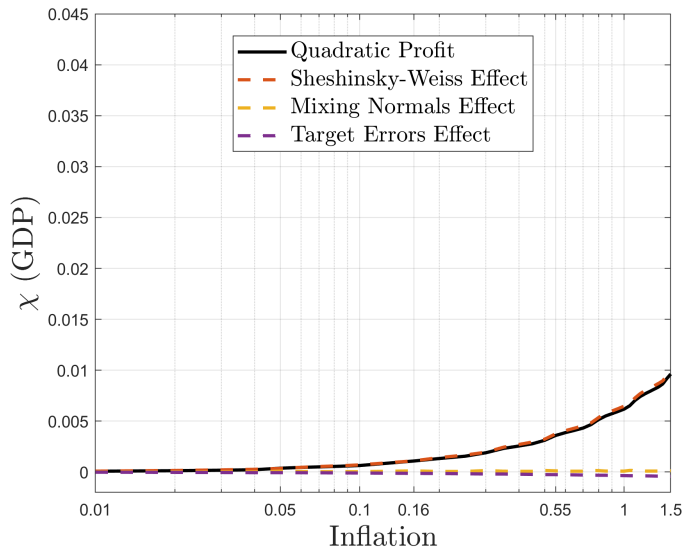
# Misallocation Costs of Inflation: Models Comparison



# Baseline Model Decomposition



# Quadratic Profit Model Decomposition



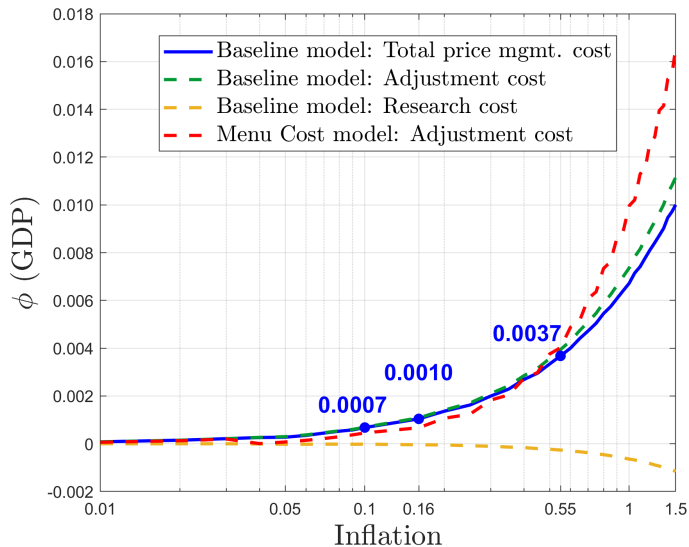
## Decomposition of $\chi(0.55) - \chi(0.16) = 74$ bp

$$\frac{\eta}{2} \Delta \text{Var}(x) = \frac{\eta}{2} \Delta \left( \underbrace{E[\text{Var}(\bar{x}|\tau)]}_{\text{Sheshinski-Weiss effect}} + \underbrace{\text{Var}[E(\bar{x}|\tau)]}_{\text{mixing normals with diff. means}} + \underbrace{\sigma^2 E(\tau)}_{\text{target errors}} \right)$$

	SW	Mixing normals	Target errors	Total	$N_a$
$\mu = 0.55$ + “behavior fixed”	21 bp	-3 bp	-4 bp	14 bp	6
$\mu = 0.55$ + optimal $\alpha, \bar{x}^*$	43 bp	16 bp	3 bp	62 bp	5.4
$\mu = 0.55$ + optimal $\omega, \alpha, \bar{x}^*$	43 bp	23 bp	8 bp	74 bp	5.4
Only menu cost (total)	6 bp	—	—	6 bp	4.1

“behavior fixed” means  $\{\omega, \alpha, \bar{x}^*\}$  fixed at  $\mu = 0.16$  values

# Price Management Costs: Research and Adjustment Activities



## Summing up

use simple NK model to quantify costs of inflation

- ▶ imperfect info useful to fit data (boosts elast. of  $N$  to  $\mu$ )
- ▶ imperfect info amplifies inflation costs
  - more action on extensive margin (wider inaction region)
  - ignorance spreads firms' return points (hedging motive)
- ▶ Non negligible inflation costs, steep gradient
  - The welfare cost of 10% inflation are 25bp of GDP in cons. equiv.
  - The welfare cost of 55% inflation are 138bp of GDP in cons. equiv.



Thank you!

## Appendix

- ▶ How to compute joint moments of price adjustments and time between adjustments  $\{\Delta p, \tau^a\}$
- ▶ Define generator of the uncontrolled state + discovery process
- ▶ From an initial condition, propagate that process forward removing mass upon adjustments
- ▶ The removed density is the joint distribution of price changes, information ages (measured at adjustment dates) and time between adjustments
- ▶ Continue in next slide...

## Appendix cont'd

- ▶ Let  $\mathcal{A}$  be the generator of the uncontrolled + observation process
- ▶ Let  $F(\bar{x}, \tau, t)$  be a time-varying measure on  $(\bar{x}, \tau)$  that keeps track of the states that have not adjusted and  $Q$  for the measure of states that have
- ▶ Let  $P(\Delta p, \tilde{\tau}, \tau^a)$  be the distribution of price changes, information age (measured at times of adjustments) and time between adjustments

## Appendix cont'd

- ▶ Let  $F(\bar{x}, \tau, 0)$  be a density integrating to 1 of states right after an adjustment e.g. a Dirac density on  $(\bar{x}^*(\tau), \tau)$
- ▶  $F(\bar{x}, \tau, t)$  solves the following PDE

$$\partial_t F = \mathcal{A}F - \alpha \cdot F$$

- ▶ Then the distributions  $Q$  and  $P$  are

$$P(\bar{x}^*(\tau) - \bar{x}, \tilde{\tau}, \tau^a) = Q(\bar{x}, \tilde{\tau}, \tau^a) = \alpha(\bar{x}, \tau) \cdot F(\bar{x}, \tilde{\tau}, \tau^a)$$

## New information at price adjustment dates

- ▶ New information (mg cost shocks) at adjustment dates has three components
- ▶  $\tau_0$ : information age at start of price spell
- ▶  $\tau^a$ : information that transpired during the price spell
- ▶  $\tau$ : information age at end of price spell
- ▶  $\implies$  new info has variance  $\tau_0 + \tau^a - \tau$

Return

## Sequential problem

- Firm with state  $(\bar{x}, \tau)$  at  $t = 0$  solves

$$v(\bar{x}, \tau) = \min_{\alpha, \omega, \bar{x}^*} \mathbb{E} \left[ \int_0^\infty e^{-\rho t} F[x(t)] dt \mid x(0) \sim \mathcal{N}(\bar{x}, \sigma^2 \tau) \right]$$

$$d\bar{x} = -\mu dt \text{ and } d\tau = dt.$$

- For illustration assume  $\alpha, \omega$  fixed.
- Developing the RHS for the flow and the non-jump term

$$v(\bar{x}, \tau) = \min_{\bar{x}^*} \mathbb{E}_0 \left[ F[x(0)]\Delta + o(\Delta) + e^{-(\rho+\alpha+\omega)\Delta} \int_\Delta^\infty e^{-\rho(t-\Delta)} F[x(t)] dt + \dots \right]$$

$$v(\bar{x}, \tau) = \min_{\bar{x}^*} \mathbb{E}_0 \left[ F[x(0)]\Delta + o(\Delta) + e^{-(\rho+\alpha+\omega)\Delta} v[\bar{x}(\Delta), \tau(\Delta)] + \dots \right]$$

$$v(\bar{x}, \tau) = \min_{\bar{x}^*} \mathbb{E}_0 \left[ F[x(0)]\Delta + o(\Delta) + e^{-(\rho+\alpha+\omega)\Delta} \{v(\bar{x}, \tau) + \partial_{\bar{x}} v \cdot (-\mu\Delta) + \partial_\tau v \cdot (\Delta)\} + \dots \right]$$

$$(\rho + \alpha + \omega)\Delta v(\bar{x}, \tau) = \min_{\bar{x}^*} \mathbb{E}_0 \left[ F[x(0)]\Delta + o(\Delta) + e^{-(\rho+\alpha+\omega)\Delta} \{ \partial_{\bar{x}} v \cdot (-\mu\Delta) + \partial_\tau v \cdot (\Delta) \} + \dots \right]$$

Denote the conditional expectation by  $\mathbb{E}_0$

## Sequential problem (cont'd)

### ► Developing the jump terms

$$\dots = \min_{\bar{x}^*} \mathbb{E}_0 [\dots + e^{-\rho\Delta} [(1 - e^{-\alpha\Delta})v(\bar{x}^*, \tau(\Delta)) + (1 - e^{-\omega\Delta})v(x(\Delta), 0)]]$$

$$\dots = \min_{\bar{x}^*} \mathbb{E}_0 [\dots + e^{-\rho\Delta} [(1 - e^{-\alpha\Delta}) [v(\bar{x}^*, \tau) + \partial_\tau v \cdot \Delta] + (1 - e^{-\omega\Delta})v(x(\Delta), 0)]]$$

$$\dots = \min_{\bar{x}^*} \mathbb{E}_0 [\dots + e^{-\rho\Delta} [\alpha\Delta v(\bar{x}^*, \tau) + o(\Delta) + \omega\Delta v(x(0), 0)]]$$

2nd to 3rd line: drift and diffusion terms times hazards are order  $\Delta^2$

### ► Putting the terms together, dividing by $\Delta$ and taking the limit as $\Delta \rightarrow 0$

$$(\rho + \alpha + \omega) v(\bar{x}, \tau) = \min_{\bar{x}^*} \mathbb{E}_0 [F[x(0)] + \partial_{\bar{x}} v \cdot (-\mu) + \partial_\tau v + \alpha v(\bar{x}^*, \tau) + \omega v(x(0), 0)]$$

$$(\rho + \alpha + \omega) v(\bar{x}, \tau) = \mathbb{E}_0 F[x(0)] + \partial_{\bar{x}} v \cdot (-\mu) + \partial_\tau v + \alpha \min_{\bar{x}^*} v(\bar{x}^*, \tau) + \omega \mathbb{E}_0 v(x(0), 0)$$

Q.E.D. [Return](#)

# Mapping Observables to Model Parameters: No Info Friction

- LHS: moments in the **data**  $\{\Delta p, \tau^a\}$
- Operators  $\tilde{E}, \widetilde{\text{Var}}$  integrate w.r.t. density of  $\{\Delta p, \tau^a\}$

$$\frac{1}{\tilde{E} \tau^a} = N_a, \quad (1)$$

$$N_a \tilde{E} \Delta p = \mu, \quad (2)$$

$$N_a \tilde{E} (\Delta p - \mu \tau^a)^2 = \sigma^2, \quad (3)$$

$$N_a \tilde{E} \tau^a \left( \Delta p - \frac{\mu}{2} \tau^a \right) = x^* - \tilde{E} x \quad (4)$$

$$\frac{1}{3} \frac{N_a}{\mu} \tilde{E} (\Delta p)^3 - (x^* - \tilde{E} x) \left( \frac{\sigma^2}{\mu} + x^* - \tilde{E} x \right) = \text{Var}(x) \quad (5)$$

Return



## Relative Entropy (skip)

- ▶ How the distribution of gaps changes with higher inflation?
- ▶ One measure is relative entropy between two densities  $m_1$  and  $m_0$  e.g.  $m_1$  corresponds to 0.6 inflation and  $m_0$  to 0.3 inflation
- ▶ Relative entropy measures  $\int_{-\infty}^{\infty} \log[n(x)] n(x) m_0(x) dx$  where  $n(x) \equiv m_1(x)/m_0(x)$
- ▶ Next figure displays  $\log[n(x)] n(x) m_0(x) dx$  as a share of relative entropy to understand important contributors

# Pricestats vs CPI data: Turkey

