

Technology Adoption and Optimal Industrial Policy

Fernando Alvarez

University of Chicago

Francisco Buera

Wash U in St. Louis

Nicholas Trachter

Richmond Fed


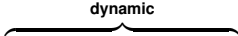
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Introduction and Summary

- ▶ Optimal "Industrial Policy" in set up often used for Big-Push
- ▶ *Dynamic* economy with complementarities, tech. adoption after paying fixed cost (non-convexities), market power & heterogeneity.

Results:

1. Economy is inefficient:  misallocation and  **technology adoption**
2. Static inefficiency stems from underproduction/use of intermediate goods: corrected by directly (or indirectly) subsidizing its use
3. Dynamic Inefficiency stems from firms valuation of tech. adoption too low relative to its cost: corrected by subsidizing adoption
4. If complementarity are large enough, multiple steady states/BGP
5. Optimal policy started at Laissez-faire BGP without tech adoption
 - Either stays there because adoption is too costly
 - Or start transition to high adoption steady state/BGP (a Big Push?)
 - No role equilibrium selection unless intertemporal elasticity is high

Selected Related Literature

- ▶ Big Push: Murphy, Schleifer and Vishny (1989), and many others
- ▶ Round-about production as complementarities: Ciccone (1996,2002), Jones (2011)
- ▶ Dynamics, multiple equilibrium paths: Matsuyama (1991) and Krugman (1991)
- ▶ Dynamics of optimal allocation w/non-convexities: Skiba (1978), Dechert and Nishimura (1983), Stachurski, Venditti and Yano (2012)
- ▶ Replacement Effect: Arrow (1962), Tirole (1988)
- ▶ Vintage Capital: Chari and Hopenhayn (1991), Bertolotti and Lanteri (2024), and many others

A MODEL WITH A GROWING FRONTIER

Set Up

- ▶ Technology frontier grows: $e^{\gamma t}$ (firms can adopt a new tech. after paying a fixed cost)
- ▶ Gap g : log of TFP distance of frontier, in time units
- ▶ At t operate technologies with gap $g \leq G(t)$ (optimal to adjust at threshold $G(t)$)
- ▶ Poisson rate q : free adoption opportunity
- ▶ Distribution (density) of Firms at time t indexed by gaps $m(g, t)$
- ▶ Law of motion for $m(g, t)$: # firms w/gap g , for $0 \leq g \leq G(t)$

$$m(g + dg, t + dt) - m(g, t)(1 - dt q) = 0 \quad (\text{discrete time})$$

$$\implies m_t(g, t) + m_g(g, t) + q m(g, t) = 0 \quad (\text{continuous time})$$

- ▶ Mass preservation, $1 = \int_0^{G(t)} m(g, t) dg$, for all $t > 0$

$$\implies \underbrace{m(0, t)}_{\text{adoption}} = \underbrace{m(G(t), t)}_{\text{reach } G(t)} + \underbrace{q}_{\text{free}} - \underbrace{m(G(t), t) G'(t)}_{\text{change } G}$$

Feasibility: adoption

- ▶ Consumption $C(t)$ of aggregate good
- ▶ Costly adoption: $\kappa(t)$ units of aggregate good; $\kappa(t) = \kappa e^{\frac{\gamma}{1-\nu}t}$
- ▶ Feasibility, $C(t) = Y(t) - \kappa(t) \left[m(0, t) - q \int_0^{G(t)} m(g, t) dg \right]$
- ▶ Preferences: $\int_0^\infty e^{-\rho t} \frac{C(t)^{1-\theta} - 1}{1-\theta} dt$

Period t technology

- ▶ Cobb-Douglas output of differentiated good w/TFP $e^{(t-g)\gamma}$

$$e^{(t-g)\gamma} b x(g, t)^\nu n(g, t)^{1-\nu}$$

(ν share of intermediate input, $1 - \nu$ labor share, b constant)

- ▶ $Y(t)$: net agg. output & $X(t)$: Intermediate Aggregate

$$\overbrace{Y(t) + X(t)}^{\equiv Q(t)} = \left[\int_0^{G(t)} \left(e^{(t-g)\gamma} b x(g, t)^\nu n(g, t)^{1-\nu} \right)^{1-\frac{1}{\eta}} m(g, t) dg \right]^{\frac{1}{1-1/\eta}}$$
$$X(t) = \int_0^{G(t)} x(g, t) m(g, t) dg$$

- ▶ Exogenous labor supply normalized to 1, so: $1 = \int_0^{G(t)} n(g, t) m(g, t) dg$

Equilibrium

- ▶ Household borrow and save, own firms, supply labor
- ▶ Monopolistic competitive firms:
 1. “Static”: set prices, hire labor, buy intermediate aggregate
 2. “Dynamic”: pay fixed cost $\kappa(t)$ & adopt frontier technology ($g = 0$)
- ▶ Prices:

Differentiated good w/gap g : $p(g, t)$; Aggregate final good $P(t)$
Wages $w(t)$; Interest rate $r(t)$
- ▶ Policy instruments - lump sum from household, $T(t)$

Revenue subsidy, s_r ; Intermediate inputs subsidy, s_x ; Labor subsidy, s_l
Adoption subsidy, s_a ; Operating profits subsidy, s_π

Households

- ▶ Budget constraint

$$0 = \int_0^{\infty} e^{-\int_0^t r(s) ds} [P(t)C(t) - \Pi(t) - w(t) + T(t)] dt ,$$

- ▶ $\Pi(t)$ profits, $T(t)$ transfers, $w(t)$ wages

- ▶ Euler equation

$$r(t) = \rho + \theta \frac{\dot{C}(t)}{C(t)} + \frac{\dot{P}(t)}{P(t)} .$$

Monopolistic Competitive Firm

- $\pi(g, t) = s_\pi \hat{\pi}(g, t)$ after subsidy profits of firm g where t

$$\hat{\pi}(g, t) \equiv \max_p \left[\frac{p}{P(t)} \right]^{-\eta} Q(t) \left[\overbrace{s_r p - e^{\gamma(g-t)} \left(\frac{w(t)}{s_l} \right)^{1-\nu} \left(\frac{P(t)}{s_x} \right)^\nu}^{\text{marginal cost}} \right],$$

- Markup over marginal cost: $p(g, t) = \frac{1}{s_r} \frac{\eta}{\eta-1} e^{\gamma(g-t)} \left(\frac{w(t)}{s_l} \right)^{1-\nu} \left(\frac{P(t)}{s_x} \right)^\nu$

- Adoption problem, value function $V(g, t) \Rightarrow G(t)$:

$$r(t)V(g, t) = \max \begin{cases} r(t) \left[V(0, t) - \kappa(t) \frac{P(t)}{s_a} \right] & \text{optimal if } g \geq G(t) \\ s_\pi \hat{\pi}(g, t) + V_g(g, t) + V_t(g, t) + q(V(0, t) - V(g, t)) \end{cases}$$

(solved using VM and SP [details](#))

Temporal Equilibrium, given $m(\cdot, t)$

- ▶ Labor allocation: independent of subsidies.
- ▶ Detrended aggregate productivity:

$$Z(t) \equiv \left[\int_0^{G(t)} e^{-\gamma g(\eta-1)} m(g, t) dg \right]^{\frac{1}{\eta-1}}$$

- ▶ Profits, (numeraire) in terms wages:

$$\pi(g, t) = s_{\pi} \frac{1}{(\eta-1)(1-\nu)} \frac{e^{-\gamma g(\eta-1)}}{Z(t)^{\frac{1}{\eta-1}}}$$

- ▶ Profits, (real) in terms of final goods:

$$\frac{\pi(g, t)}{P(t)} = e^{\frac{\gamma}{1-\nu} t} \frac{s_{\pi}}{s_x} \frac{\left[s_r s_x \left(\frac{\eta-1}{\eta} \right) \right]^{\frac{1}{1-\nu}}}{(1-\nu)(\eta-1)} \frac{e^{-\gamma g(\eta-1)}}{Z(t)^{\frac{(\eta-1)(1-\nu)-1}{1-\nu}}}$$

- ▶ Real profits increasing in $Z(t)$ if $(\eta-1)(1-\nu) < 1$

$s_e = s_r s_x$ is a sufficient statistic for temporary equilibrium

- ▶ To simplify consider model with m concentrated in one value g .
- ▶ Obviously allocation is labor is efficient, normalize $w/s_l = 1$.
- ▶ Firms optimal price $p = \frac{\eta}{\eta-1} \frac{1}{s_r} (P/s_x)^\nu$
- ▶ Equilibrium $p = P$ so $P/s_x = \left(\frac{\eta}{\eta-1} \frac{1}{s_r s_x} \right)^{1/(1-\nu)}$
- ▶ Optimal choice of input: $\frac{(P/s_x)x}{(w/s_l)n} = \frac{\nu}{1-\nu}$
- ▶ In equilibrium $n = 1$ and $(w/s_l) = 1$ hence $x = \frac{1}{(P/s_x)} \frac{\nu}{1-\nu}$
- ▶ Thus, equilibrium value of x is monotone increasing in $s_e \equiv s_r s_x$
- ▶ There is a finite efficient value of x , achieved with $s_e \equiv \frac{\eta}{\eta-1}$

Aggregate Production Function, given $m(\cdot, t)$

- Aggregate output at t depends only on $m(\cdot, t)$ and $s_e \equiv s_r s_x$

$$\underbrace{e^{\frac{\gamma}{1-\nu}t}}_{\text{trend}} \underbrace{Y(m(\cdot, t), s_e)}_{\text{detrended output}} \equiv e^{\frac{\gamma}{1-\nu}t} \underbrace{A(s_e)}_{\text{Misallocation}} \underbrace{F(m(\cdot, t))}_{\text{Prod Function}}$$

- Loss on TFP: Static 'misallocation' (stems from distortions)

$$A(s_e) \equiv \frac{1}{1-\nu} \left[\frac{1}{s_e} \frac{\eta}{\eta-1} - \nu \right] \left[s_e \frac{\eta-1}{\eta} \right]^{\frac{1}{1-\nu}}$$

- Aggregate production function

$$F(m(\cdot, t)) \equiv Z(t)^{\frac{1}{1-\nu}} = \left[\int_0^{G(t)} e^{-\gamma g(\eta-1)} m(g, t) dg \right]^{\frac{1}{(\eta-1)(1-\nu)}}$$

- Curvature parameter (compl. vs subs. or convex vs conc.)

$$\zeta \equiv \frac{1}{(\eta-1)(1-\nu)} \gtrless 1$$

Static Efficient Allocation $\mathcal{Y}(m)$

- Fix m . Maximize net detrended aggregate output $\mathcal{Y}(m)$:

choice of date t allocation s.t. mkt clearing intermediate, labor & prod. functions

$$\implies \mathcal{Y}(m) = Z(t)^{\frac{1}{1-\nu}}$$

- If $\nu = 0$, then $\mathcal{Y}(m) = Y(m, \mathbf{s}_e)$

- If $\nu > 0$, then $\mathcal{Y}(m) \geq Y(m, \mathbf{s}_e)$ with equality if $\mathbf{s}_e = \mathbf{s}_e^* \equiv \frac{\eta}{\eta-1}$

- m^ϵ : m perturbed so that ϵ density is moved from g_2 to g_1 :

1. $\mathcal{Y}(m^\epsilon)$ is concave in ϵ and $m \iff \zeta \equiv \frac{1}{(\eta-1)(1-\nu)} \leq 1$

2. $\frac{d\mathcal{Y}(m^\epsilon)}{d\epsilon} \Big|_{\epsilon=0} = \frac{\pi(g_1, t) - \pi(g_2, t)}{\mathbf{s}_\pi P(t) / \mathbf{s}_x} \left[\frac{1}{\mathbf{s}_e} \left(\frac{\eta}{\eta-1} \right) \right]^{\frac{1}{1-\nu}}$

\implies Social marginal benefit \propto (temp. eqbm) real profits

Efficient Allocation - Two period Mickey-Mouse model

- ▶ At an Equilibrium, adoption gives:

$$\frac{\pi(0, t) - \pi(G(t), t)}{P(t)/s_a} = \kappa(t)$$

- ▶ For the planner efficient adoption gives:

$$\left. \frac{d\mathcal{Y}(m(\cdot, t))}{d\epsilon} \right|_{\epsilon=0} = \kappa(t)$$

- ▶ Previous results gives

$$\underbrace{\frac{d\mathcal{Y}(m(\cdot, t))}{d\epsilon}}_{\text{social benefit}} = \left[\frac{1}{s_e} \left(\frac{\eta}{\eta - 1} \right) \right]^{\frac{1}{1-\nu}} \frac{s_e}{s_r s_a s_\pi} \times s_a \underbrace{\frac{\pi(0, t) - \pi(G(t), t)}{P(t)}}_{\text{private benefit}}$$

- ▶ Define $s_d = s_\pi s_a s_r$, decentralize efficient $s_e^* = s_d^* = \frac{\eta}{\eta-1}$
- ▶ Result extends exactly the same to infinite horizon model.

Efficient Allocation - Infinite Horizon Model

- ▶ Given initial $m_0(g)$ all g , maximize

$$\int_0^{\infty} e^{-\bar{\rho}t} \frac{c(t)^{1-\theta} - 1}{1-\theta} dt, \text{ by choosing path of adoption } G'(t) \text{ s.t.}$$

- Law of motion of entire distribution

$$0 = m_t(g, t) + m_g(g, t) + q m(g, t), \text{ all } g \in [0, G(t)], t \geq 0$$

- Resource constraint: $c(t) = \mathcal{Y}(m(\cdot, t)) - \kappa(m(0, t) - q)$

- ▶ Implementation of efficient allocation

- Eqbm and nec. conditions coincide

- If $\nu = 0$, $S_d \equiv S_{\pi} S_r S_a = \frac{\eta}{\eta-1}$

- If $\nu > 0$, $S_e \equiv S_r S_x = \frac{\eta}{\eta-1}$ and $S_d \equiv S_{\pi} S_r S_a = \frac{\eta}{\eta-1}$

- Possible multiple equilibrium paths under optimal policy

- unique path: if $\zeta \leq 1$
 - if multiple eqbm path: role of coordination

Solving for a BGP: fixed point

Economy grows at rate $\frac{\gamma}{1-\nu}$, $G(t) = G^*$ and interest rates are constant

Aggregation: $G \rightarrow Z^*$

$$Z^* = \left[\int_0^G e^{-\gamma g(\eta-1)} \frac{q e^{-qg}}{1 - e^{-qG}} dg \right]^{\frac{1}{\eta-1}}$$

Higher aggregate adoption \implies higher “TFP” Z

Optimization of a firm: $Z \rightarrow G^*$

$$\overbrace{\zeta \left[Z^{\eta-1} \right]^{\zeta-1} R(G^*) / (q + \bar{\rho})}^{\text{Net discounted gain}} = \overbrace{\kappa \frac{s_e}{s_d} \left(\frac{1}{s_e} \frac{\eta}{\eta-1} \right)^{\frac{1}{1-\nu}}}^{\text{Adjusted fixed cost}}$$

where $R(G) = 1 - e^{-\gamma(\eta-1)G} - \frac{\gamma(\eta-1)}{q+\rho+\gamma(\eta-1)} [1 - e^{-(q+\rho+\gamma(\eta-1))G}]$

Higher TFP Z : has two effects on adoption

1. pro-competitive effect (lower mkt share) \implies lower adoption incentives
2. lower price of adoption good \implies higher adoption incentives

Strength of Complementarities and BGPs

$\zeta \leq 1$: *one* BGP

(pro-competitive effect dominates)

If $\bar{\kappa}$ 'large', then without costly adoption

Otherwise, then with costly adoption

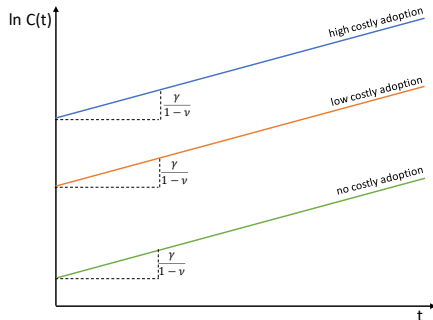
$\zeta > 1$: *multiple* BGPs are possible

(lower price adoption dominates)

1 without costly adoption

1 with infrequent costly adoption

1 with frequent costly adoption



A MODEL WITH A STATIC FRONTIER

Setup

- ▶ Frontier normalized to 1. No free adoption, $q = 0$
- ▶ Firm with gap $z \rightarrow$ productivity $e^{-z} < 1$
- ▶ Pay fixed cost & jump to frontier; can recoup fixed cost & get back to z
 $V(z, t)$
- ▶ Define $K(t)$ = mass of firms at frontier ; m_0 constant through t

$$K = 1 - \int_0^{\hat{G}(K)} m_0(z) dz \implies \dot{K}(t) = -m_0(G(t)) \dot{G}(t)$$

- ▶ Feasibility: $\kappa \dot{K}(t) + C(t) = A(s_e)F(K(t))$
- ▶ Aggregate Production: $F(K) = \left[\int_0^{\hat{G}(K)} e^{-z(\eta-1)} m_0(z) dz + K \right]^\zeta$

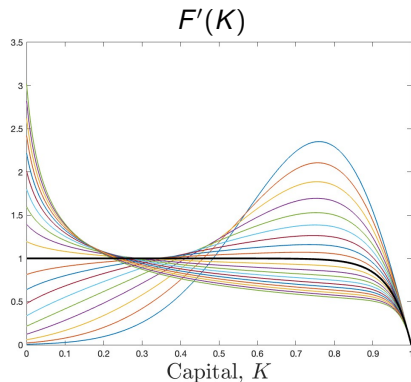
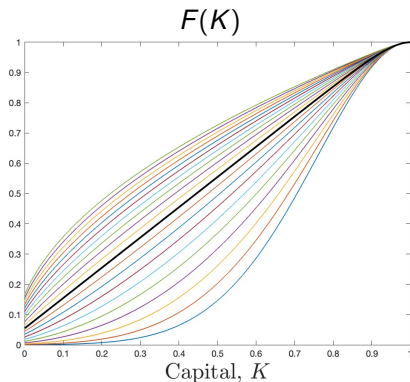
\implies Akin to Neoclassical Growth Model

- K : capital stock
- Same law of motion for K
- Difference: $F(K)$ is not necessarily concave!

Shape of Production Function $F(K)$

► Properties of $F(K)$ as function of ζ

1. If $\zeta \leq 1$, globally concave
2. Always concave near $K = 1$
3. If $\zeta > 1$ and regularity, then $F(\cdot)$ is S-shaped, $F'(\cdot)$ inverse U



Equilibrium: Neoclassical Growth model w/tax!

- ▶ Fix s_e, s_d and $K(0) = K_0$
- ▶ Nec. and suff. conditions for interior eq. is that $\{C(t), K(t)\}$ solve

$$C(t) + \kappa \dot{K}(t) = A(s_e)F(K(t)), \quad \theta \frac{\dot{C}(t)}{C(t)} = B(s_e, s_d)A(s_e)F'[K(t)]/\kappa - \rho$$

where $B(s_e, s_d) \equiv \left(\frac{1-\nu}{\frac{1}{s_e} \frac{\eta}{\eta-1} - \nu} \right) \frac{s_d}{s_e}$ & $0 = \lim_{T \uparrow \infty} e^{-\rho T} C(T)^{-\theta} A(s_e)F[K(T)]$

- ▶ Interpretation: NGM with $1 - B(1, 1)$ tax on capital returns
($B(1, 1) = 1 - \frac{1}{\eta}$ when $\nu = 0$)

Equilibrium: Neoclassical Growth model w/tax!

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$$\text{where } B(s_e, s_d) \equiv \left(\frac{1-\nu}{\frac{1}{s_e} \frac{\eta}{\eta-1} - \nu} \right) \frac{s_d}{s_e} \text{ \& } 0 = \lim_{T \uparrow \infty} e^{-\rho T} C(T)^{-\theta} A(s_e)F[K(T)]$$

- ▶ Interpretation: NGM with $1 - B(1, 1)$ tax on capital returns
($B(1, 1) = 1 - \frac{1}{\eta}$ when $\nu = 0$)

Interior SS

Solves $B(s_e, s_d)A(s_e)F'(K^*)/\kappa = \rho$

- ▶ If $\zeta \leq 1$: at most one
- ▶ If F is S-shaped & ζ large enough
 K_L^* : source, or spiral source (θ^*)
 K_H^* : saddle
 $K_L^* < K_H^*$

SS with No Adoption

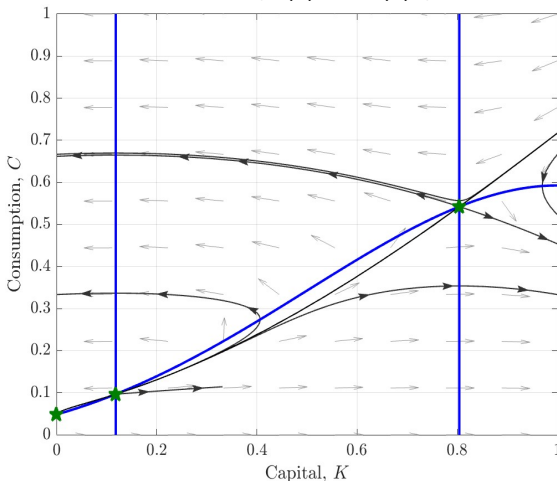
If $B(s_e, s_d)A(s_e)F'(0)/\kappa < \rho$

- ▶ $K^* = 0$ and $C^* = A(s_e)F(0)$
- ▶ Locally stable (if $\theta > \theta^*$)
- ▶ Convergence in finite time

Equilibrium w/Laissez-Faire ($s_e = s_d = 1$), $\zeta > 1$,

- ▶ 3 steady states (green stars), middle one unstable.

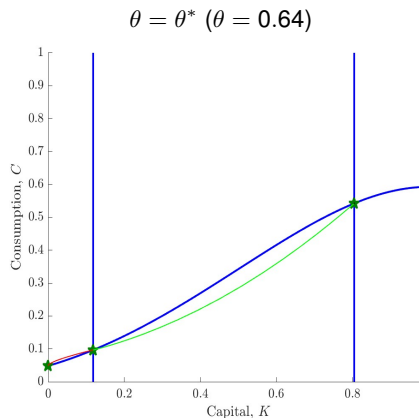
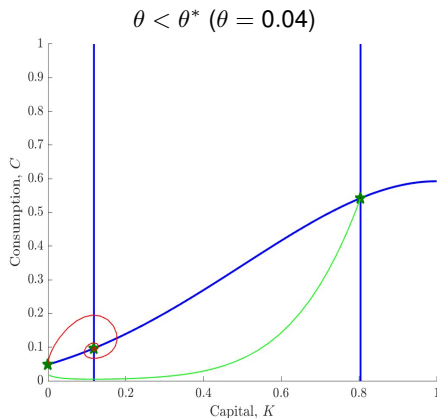
$$1 = \theta > \theta^* \quad (u(c) = \log(c))$$



- ▶ The case of $\zeta < 1$ is just like the Neoclassical Growth Model

Multiplicity of Eqbm Paths for $\zeta > 1$ and low θ

- ▶ Let $s_e = s_d = 1$



- ▶ Low θ case has multiple equilibrium path for $K(0) \in [0, 1.9]$

Planner's Problem

$$\max_{C(\cdot)} \int_0^{\infty} e^{-\rho t} U(C(t)) dt \text{ subject to } \kappa \dot{K}(t) = F(K(t)) - C(t)$$

Necessary conditions:

1. Euler eq. and Transversality condition hold
2. K^* is an optimal steady state if $F(K^*) = C^*$ and $\rho = F'(K^*)/\kappa$
 - ▶ If $\zeta > 1$ these are *only* necessary. When F is S-shaped there can be interior solutions $K_L^* < K_H^*$
 1. K_L^* cannot be stable
 2. If $\rho < F'(0)/\kappa$, K_H^* from any $K(0)$ is locally stable (saddle)
 3. If $\theta < \theta^*$ multiple paths satisfying EE + TC.
- ▶ Decentralization: eliminate both distortions:
 $s_e^* = s_d^* = \frac{\eta}{\eta-1} \implies A(s_e^*) = B(s_d^*) = 1$

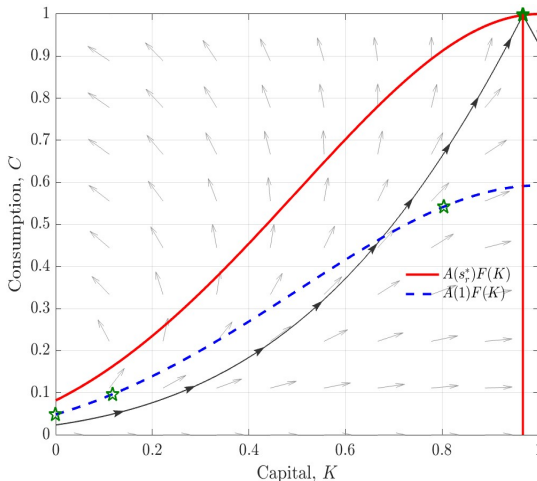
Trap or No trap?

Consider an economy that starts at SS $K^* = 0$ w/no adoption

- ▶ If $\left(\frac{\eta-1}{\eta}\right)^{\frac{1}{1-\nu}} F'(0) < \kappa\rho < F'(0)$
 - Only one interior SS w/high adoption survives with subsidy
 - Long transition from $K^* = 0$ to interior SS w/high adoption (i.e. implements a Big Push)
 - Laissaz Faire SS w/no adoption is a **TRAP**, optimal policy moves the economy away from it
 - See Figure
- ▶ If $F'(0) < \kappa\rho$?
 - The three SS remain even w/optimal policy
 - Economy remains in the SS w/no adoption (but with no static misallocation)
 - The SS with no adoption is **NOT A TRAP**

Optimal exit of trap: $s_e^* = s_d^* = \eta/(\eta - 1)$

- Assume that $\zeta > 1$ and that $\left(\frac{\eta-1}{\eta}\right)^{\frac{1}{1-\nu}} F'(0) < \kappa\rho < F'(0)$



Optimal policy pushes the economy out of the 'trap', which converges to the higher steady state, far away from no adoption SS.

Conclusions

- ▶ Two versions of dynamics model of adoption:
 1. Growing frontier \approx Vintage Capital Model
 2. Fixed frontier \approx Neoclassical Growth Model
- ▶ In both cases, static inefficiency acts by reducing output.
- ▶ In both cases dynamic inefficiency acts as an tax on investment
- ▶ Optimal policy eliminates static distortions and investment tax
 - Menu of 5 subsidies/tax to achieve efficiency
 - Optimal involves only two combinations
- ▶ Fixed frontier model: full analysis of dynamics
- ▶ Large effects due to strategic complementarities.
- ▶ No role for Eqbm selection out of a trap, unless θ low enough
- ▶ If θ small enough, temporary higher s_d used as Eqbm selection.

Efficient Allocation

- Given initial m_0 , maximize

$$\int_0^{\infty} e^{-\bar{\rho}t} \frac{c(t)^{1-\theta} - 1}{1-\theta} dt$$

by choosing a time differentiable path of threshold $\{G(t)\}$

- subject to the constraints for all $t \geq 0$:

$$e^{-\bar{\rho}t} \lambda(g, t) : 0 = m_t(g, t) + m_g(g, t) + q m(g, t), \text{ for } 0 \leq g \leq G(t)$$

$$e^{-\bar{\rho}t} \omega(t) : 0 = 1 - \int_0^{G(t)} m(g, t) dg,$$

where $e^{-\rho t} \lambda(g, t)$ and $\omega(t)$ are Lagrangian multipliers and where

$$c(t) = \frac{N}{1-\nu} Z(t)^{\frac{1}{1-\nu}} - \kappa (m(0, t) - q) \text{ with}$$

$$Z(t) = \left[\int_0^{G(t)} e^{-\gamma g(\eta-1)} m(g, t) dg \right]^{\frac{1}{\eta-1}}$$

Adoption problem characterization

- ▶ Given path $\{\pi(\cdot, t), P(t), r(t)\}$ solve for path of threshold $\{G(t)\}$

- ▶ For $0 \leq g \leq G(t)$:

$$r(t)V(g, t) = \pi(g, t) + V_g(g, t) + V_t(g, t) + q(V(0, t) - V(g, t))$$

- ▶ For $g \geq G(t)$:

$$V(g, t) = V(0, t) - s_a \kappa(t)P(t) \implies 0 = V_g(g, t)$$

- ▶ Value Matching:

$$V(G(t), t) = V(0, t) - \kappa(t)P(t) \text{ for all } t > 0$$

- ▶ Smooth pasting:

$$0 = V_g(G(t), t)[G'(t) - 1] \text{ for all } t > 0$$

Characterization of Efficient Allocation

- ▶ Multiplier for law of motion m :

$$\begin{aligned}\bar{\rho}\lambda(g, t) = & c(t)^{-\theta} Z(t)^{\frac{1}{1-\nu}} \pi(g, t) + \lambda_t(g, t) + \lambda_g(g, t) \\ & - \omega(t) + q(\lambda(0, t) - \lambda(g, t)) \text{ for } t \geq 0 \text{ \& } g \in [0, G(t)]\end{aligned}$$

- ▶ Boundary conditions:

$$\begin{aligned}\lambda(0, t) &= c(t)^{-\theta} \kappa, \text{ for all } t > 0 \\ \lambda(G(t), t) &= 0, \text{ all } t > 0 \\ \lambda_g(G(t), t) &= 0, \text{ all } t > 0\end{aligned}$$

- ▶ Transversality:

$$0 = \lim_{T \rightarrow \infty} e^{-\bar{\rho}T} \lambda(g, T) m(g, T) \text{ for all } 0 \leq g < \lim_{T \rightarrow \infty} G(T)$$

- ▶ These conditions + feasibility are necessary.
- ▶ If $\zeta \leq 1$ they are sufficient. [▶ back](#)

Firm's Problem

- ▶ $V(z, t)$, the value of a z at t that has not adopted the frontier

$$V(z, t) = \max_{\tau \geq t} \int_t^{\tau} e^{-\int_t^s r(\tilde{s}) d\tilde{s}} \pi(z, s) ds + e^{-\int_t^{\tau} r(\tilde{s}) d\tilde{s}} \left[V^0(z, \tau) - s_a(\tau) \kappa P(\tau) \right]$$

- ▶ $V^0(z, t)$, the value of a z firm that has adopted the frontier

$$V^0(z, t) = \max_{\{\tau \geq t\}} \int_t^{\tau} e^{-\int_t^s r(\tilde{s}) d\tilde{s}} \pi(0, s) ds + e^{-\int_t^{\tau} r(\tilde{s}) d\tilde{s}} [V(\tau, z) + \kappa s_a(\tau) P(\tau)]$$