## Aggregate Uncertainty, HANK, and the ZLB

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## Disclaimer

The views expressed herein are those of the authors and do not necessarily reflect those of the Bank of Italy or its executive board.

## Outline

## Introduction

Simple Model
HANK Model
Solution Approach
Results

Other Applications
Conclusions

## Introduction (1) - Motivation

Figure 1: Mon. Policy, Micro-Macro uncertainty


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- We are interested in understanding this interaction..
- via HANK-DSGE-model

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4. HANK + ZLB + Aggregate Uncertainty: Fernández-Villaverde et al. (2021), Kase et al. (2022), Schaab (2020)

## Introduction (3) - Contribution

- Novel solution strategy for HANK models w/aggregate uncertainty (AU) and ZLB:
- In practice: take standard HANK, add ZLB, add tractable AU, compare to PF
- Solution allows to quantify interactions between AU-ZLB-HA


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|  | Perf. Fores. | Agg. Unc. |  | Perf. Fores. | Agg. Unc. |
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1. Quantify effect of aggregate uncertainty in HANK at the ZLB (E vs D)
2. Quantify effect of aggregate uncertainty in RANK at the ZLB ( $C$ vs $B$ )
3. Decompose the role of HA in the amplification (E-D vs C-B)

## Introduction (3.1) - Contribution Extra

- Novel solution strategy...
- but not limited to ZLB, can accomodate more general non-linearities (kinky PC, aggregate borrowing constraints/financial accelerator, downward wage rigidity...)


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$$
\begin{align*}
Y_{t}^{-\sigma} & =\frac{\beta_{t} R_{t}}{\beta R_{s s}} \mathbb{E}_{t} Y_{t+1}^{-\sigma}  \tag{1}\\
R_{t} & =\max \left\{\underline{R}, R_{s s} Y_{t}^{\phi}\right\}  \tag{2}\\
R_{s s} & =\frac{1}{\beta\left\{p\left(z_{u}^{-\sigma}\right)+(1-p)\left[\left(\frac{1-\lambda z_{u}}{1-\lambda}\right)^{-\sigma}\right]\right\}}
\end{align*}
$$

## Simple Model (2) - Solution

$$
\begin{align*}
Y_{t} & =f\left(\mathbb{E}_{t} Y_{t+1}^{-\sigma}, \beta_{t} \mid \beta, \sigma, \phi, \underline{R}, R_{s s}\right) \\
& = \begin{cases}\left(\frac{\beta_{t}}{\beta} \mathbb{E}_{t} Y_{t+1}-\sigma\right)^{-\frac{1}{\sigma+\phi}} & \text { if } \beta_{t} \leq \beta\left(\frac{R_{s s}}{\underline{R}}\right)^{\frac{\sigma+\phi}{\phi}}\left(\mathbb{E}_{t} Y_{t+1}^{-\sigma}\right)^{-1}, \\
\left(\frac{\beta_{t}}{\beta} \frac{R}{R_{s s}} \mathbb{E}_{t} Y_{t+1}^{-\sigma}\right)^{-\frac{1}{\sigma}} & \text { otherwise }\end{cases} \tag{3}
\end{align*}
$$

- Higher future MU (or larger discount factor) leads to larger recession


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- AU) $\beta_{1}=\beta_{L}>\beta$ with probability $\mu, \beta_{1}=\beta$ otherwise
- PF) $\beta_{1}=\beta_{D E T}$ such that same effect absent ZLB (i.e. $\underline{R}=-\infty$ )


## Simple Model (4) - Graphical Intuition

Figure 2: Equilibrium in the Simple Model


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1. ZLB amplifies effect of shock because interest rate higher than it would have been. True even with PF...
2. AU shock interacts with ZLB, implies further amplification, because of Jensen's inequality. True even with RA...
3. So what is the role of HA in this amplification?

- in the steady state (closer to the ZLB in the steady state because of precautionary savings - kink more to the left)
- in the business cycle (lowers $R_{t}$ towards ZLB because of precautionary savings and MPCs - steeper slope)


## HANK Model (1) - Overview

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- Standard one-asset HANK model (McKay et al. (2016), Guerrieri and Lorenzoni (2017)):

■ Demand side (idiosyncratic risk, borrowing constraint)

- New-Keynesian Phillips Curve
- Supply of bonds from government

■ Taylor rule + ZLB

- Preference shock


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- Supply of bonds from government
- Taylor rule + ZLB
- Preference shock
- Calibration: standard parameter values + Great Recession


## HANK Model (2) - Households

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- Household $i$ with assets $a_{i t-1}$ and shock $z_{i t}$ maximizes:

$$
V_{t}\left(z_{i t}, a_{i t-1}\right)=\max _{c_{i t}, a_{i t} \geq \underline{a}} \frac{c_{i t}^{1-\sigma}}{1-\sigma}+\beta_{t} \mathbb{E}_{t} V_{t+1}\left(z_{i t+1}, a_{t}\right)
$$

subject to:

$$
c_{i t}+\frac{a_{i t}}{R_{t}}=\frac{a_{i t-1}}{\Pi_{t}}+z_{i t}\left(Y_{t}-t_{t}\right)
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Aggregate Asset Demand

$$
A_{t}=\int g_{t}^{a}(z, a) d D_{t}(z, a)
$$

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- New Keynesian Phillips Curve (from Rotemberg):

$$
\left(\Pi_{t}-\bar{\Pi}\right) \Pi_{t}=\mathbb{E}_{t} \beta_{t}\left(\frac{Y_{t+1}}{Y_{t}}\right)^{1-\sigma} \times\left(\Pi_{t+1}-\bar{\Pi}\right) \Pi_{t+1}+\tilde{\kappa}\left[Y_{t}^{\omega+\sigma}-1\right]
$$

- Government Budget and Fiscal Policy

$$
T_{t}+\frac{b_{t}}{R_{t}}=\frac{b_{t-1}}{\Pi_{t}} \quad b_{t}=\bar{b}
$$

- Market Clearing

$$
b_{t}=\int g_{t}^{a}(a, z) d D_{t}(z, a)
$$

- Monetary Policy

$$
R_{t}=\max \left\{1, \bar{R}\left(\frac{\Pi_{t}}{\bar{\Pi}}\right)^{\phi_{\pi}}\left(\frac{Y_{t}}{\bar{Y}}\right)^{\phi_{Y}}\right\}
$$

## HANK Model (4) - Shock Structure

Graphical Representation of Deterministic and Stochastic Shocks


- economy at steady state $(t=-1)$
- time preference shock $\beta$ materializes: $\beta_{0}=\beta_{L}$
- every period: probability $1-\mu$ to revert (and a contingency realizes)
- Compare to deterministic shock: $\beta_{t}^{D E T}=\mathbb{E}_{0} \beta_{t}$
- no restrictions on values, only on $\mu$ (must be the same).


## HANK Model (4) - Shock Structure

Graphical Representation of Deterministic and Stochastic Shocks


$$
\beta_{t}=\left\{\begin{array}{ll}
\beta & \text { w.p. }=1, \text { if } \beta_{t-1}=\beta  \tag{4}\\
\beta & \text { w.p. }=1-\mu, \text { if } \beta_{t-1}=\beta_{L} \\
\beta_{L} & \text { w.p. }=\mu, \text { if } \beta_{t-1}=\beta_{L}
\end{array} \quad \beta_{t}^{P F}=\mu^{t} \beta_{L}+\left(1-\mu^{t}\right) \beta\right.
$$

## HANK Model (5) - Calibration

Table 1: Calibration

| Parameter | Value | Source | Note |
| :---: | :---: | :---: | :---: |
| $\sigma$ | 1.5 | Smets and Wouters (2007) | EIS |
| $\beta$ | 0.9805 | Calibrated | Discount Factor |
| $\kappa$ | 0.01 | Eggertsson et al. (2021) | NKPC |
| $\Pi$ | $1.02^{0.25}$ | Standard | Inflation target |
| $\phi_{\pi}$ | 1.5 | Standard | Monetary Policy |
| $\phi_{y}$ | 0.125 | Standard | Monetary Policy |
| z |  | Guerrieri and Lorenzoni (2017) | Idiosyncratic Shocks |
| Q |  | Guerrieri and Lorenzoni (2017) | Idiosyncratic Shocks |
| $\mu$ | 0.9 | Eggertsson et al. (2021) | Switching Probability |
| $\beta_{L}$ | 0.993 | Calibrated | Shock |
| T | 300 | - | Horizon Truncation |
| $\tau^{\max }$ | 100 | - | Largest Contingency |

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- potentially computationally burdensome
- some solutions: Schaab (2020), Fernández-Villaverde et al. (2021), Kase et al. (2022)
- We instead solve the model in the space of sequences
- shock structure $\Longrightarrow$ finite \# of paths the economy can follow


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Notes: x -axis is time $t, \mathrm{y}$-axis is contingency $\tau$.

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Solution: large system of equations $\left(\tau^{\max } \times(T+1) \times n X\right)$. We split diagonal/contingencies

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- Value functions become

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V_{t}\left(z_{i t}, a_{i t-1}\right) & =\max _{c_{i t}, a_{i t} \geq \underline{a}} \frac{c_{i t}^{1-\sigma}}{1-\sigma}+\beta_{t} \mathbb{E}_{t}\left[\mu V_{t+1}\left(z_{i t+1}, a_{t}\right)+(1-\mu) V_{t+1}^{t+1}\left(z_{i t+1}, a_{t}\right)\right] \\
V_{t}^{\tau}\left(z_{i t}, a_{i t-1}\right) & =\max _{c_{i t}, a_{i t} \geq \underline{a}} \frac{c_{i t}^{1-\sigma}}{1-\sigma}+\beta_{t}^{\tau} \mathbb{E}_{t} V_{t+1}^{\tau}\left(z_{i t+1}, a_{t}\right)
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\end{aligned}
$$

- (linearized) NK Phillips curve becomes

$$
\begin{aligned}
& \hat{\Pi}_{t}=\beta\left[\mu \hat{\Pi}_{t+1}+(1-\mu) \hat{\Pi}_{t+1}^{t+1}\right]+\kappa \hat{Y}_{t} \\
& \hat{\Pi}_{t}^{\tau}=\beta \hat{\Pi}_{t+1}^{\tau}+\kappa \hat{Y}_{t}^{\tau}
\end{aligned}
$$

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- Numerically, an equilibrium is represented by systems of equations

$$
\begin{align*}
& 0=\mathbf{F}^{P F}\left(\mathbb{X}^{\tau}, \mathbb{Z}^{\tau} ; X_{\tau-1}, D_{\tau}^{\tau}\right)  \tag{5}\\
& 0=\mathbf{F}^{T S}\left(\mathbb{X}^{T S}, \mathbb{Z}^{T S} ; \mathbb{V}_{1}^{P F}, \mathbb{X}_{1}^{P F}\right) \tag{6}
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$$

- where $\mathbb{X}^{\tau}\left(\mathbb{Z}^{\tau}\right)$ contains all the aggregate variables (shocks) in contingency $\tau$
- $\mathbb{X}^{T S}\left(\mathbb{Z}^{T S}\right)$ contains all the aggr. variables (shocks) on the " uncertain" diagonal
- $\mathbb{V}_{1}^{P F}, \mathbb{X}_{1}^{P F}$ contain all the "forward looking" information relevant for the diagonal


## Solution Approach (4) - Algorithm Details



1. Guess path of state variable(s) on uncertain path

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1. Guess path of state variable(s) on uncertain path
2. Solve the $\tau^{\text {max }}$ PF paths


$$
\begin{aligned}
0 & =\mathbf{F}^{P F}\left(\mathbb{X}^{\tau}, \mathbb{Z}^{\tau} ; X_{\tau-1}, D_{\tau}^{\tau}\right) \\
d \mathbb{X}^{\tau} & =\mathbf{F}_{X}^{P F-1}\left(F_{D}^{P F} d D_{\tau}^{\tau}+\mathbf{F}_{X_{\tau-1}}^{P F} d X_{\tau-1}\right) \\
\mathbf{F}_{D}^{P F} d D_{\tau}^{\tau} & \approx \underbrace{\mathbf{F}^{P F}\left(\mathbb{X}_{s s}^{P F} \mid D_{\tau}^{\tau}, X_{s s}\right)}_{y_{s s}^{\prime \prime}\left(\Lambda_{s s}^{\prime}\right)^{-\tau} d D_{\tau}^{\tau}}-\mathbf{F}^{P F}\left(\mathbb{X}_{s s}^{P F} \mid D_{s s} X_{s s}\right)
\end{aligned}
$$

- use Sequence Space Jacobian + OccBin
- collect value functions and forw. looking vars at first period of PFs


## Solution Approach (4) - Algorithm Details

1. Guess path of state variable(s) on uncertain path
2. Solve the $\tau^{\text {max }}$ PF paths

3. Given the value functions and forw. looking vars, solve the uncertain path*

$$
\begin{aligned}
0 & =\mathbf{F}^{T S}\left(\mathbb{X}^{T S}, \mathbb{Z}^{T S} ; \mathbb{V}_{1}^{P F}, \mathbb{X}_{1}^{P F}\right) \\
d \mathbb{X}^{T S} & =\left(\mathbf{F}_{X}^{T S}\right)^{-1}\left(\mathbf{F}_{\mathbb{Z}}^{T S} d \mathbb{Z}+\mathbf{F}_{\mathbb{X}}^{T S} d \mathbb{X}_{1}^{P F}+\mathbf{F}_{V}^{T S} d \mathbb{V}_{1}^{P F}\right) \\
\mathbf{F}_{\mathbb{V}}^{T S} d \mathbb{V}_{1}^{P F} & \approx \mathbf{F}^{T S}\left(\mathbb{X}_{s s}, \mathbb{Z}_{s S} \mid \mathbb{X}_{s s}, \mathbb{V}_{1}^{P F}\right)-\mathbf{F}^{T S}\left(\mathbb{X}_{s s}^{T S}, \mathbb{Z}_{s s} \mid \mathbb{X}_{s S}^{T S}, \mathbb{V}_{s s}\right)
\end{aligned}
$$

- use Sequence Space Jacobian (modified for AU) + OccBin
- recover new set of state variables


## Solution Approach (4) - Algorithm Details



1. Guess path of state variable(s) on uncertain path
2. Solve the $\tau^{\text {max }}$ PF paths
3. Given the value functions and forw. looking vars, solve the uncertain path*
4. Iterate until convergence

## Solution Approach (4) - Algorithm Details



1. Guess path of state variable(s) on uncertain path
2. Solve the $\tau^{\text {max }}$ PF paths
3. Given the value functions and forw. looking vars, solve the uncertain path*
4. Iterate until convergence
5. (optional) Use quasi-Newton method for higher order

## Results (0) - Fixing ideas on what we are after



Measuring amplification due to uncertainty:

## Results (0) - Fixing ideas on what we are after



Measuring amplification due to uncertainty:

- Aggregate Uncertainty vs Deterministic Counterfactual


## Results (0) - Fixing ideas on what we are after



Measuring amplification due to uncertainty:

- Aggregate Uncertainty vs Deterministic Counterfactual
- Shocks with the same expected values from $t=0$ perspective


## Results (0) - Fixing ideas on what we are after



Measuring amplification due to uncertainty:

- Aggregate Uncertainty vs Deterministic Counterfactual
- Shocks with the same expected values from $t=0$ perspective
- IRF-AU: $\mathbb{E}_{0} Y_{t}-\bar{Y}$, weighted average of all contingencies. IRF-PF: $Y_{t}^{P F}-\bar{Y}$


## Results (0) - Fixing ideas on what we are after



Measuring amplification due to uncertainty:

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- IRF-AU: $\mathbb{E}_{0} Y_{t}-\bar{Y}$, weighted average of all contingencies. IRF-PF: $Y_{t}^{P F}-\bar{Y}$
- Amplification if $\left|\mathbb{E}_{0} Y_{t}-Y_{t}^{P F}\right| \gg 0$


## Results (0) - Fixing ideas on what we are after



Measuring amplification due to uncertainty:

- Aggregate Uncertainty vs Deterministic Counterfactual
- Shocks with the same expected values from $t=0$ perspective
- IRF-AU: $\mathbb{E}_{0} Y_{t}-\bar{Y}$, weighted average of all contingencies. IRF-PF: $Y_{t}^{P F}-\bar{Y}$
- Amplification if $\left|\mathbb{E}_{0} Y_{t}-Y_{t}^{P F}\right| \gg 0$
- Quantification with PDV: $\sum_{t=0}^{\infty} \beta^{t}\left(\mathbb{E}_{0} Y_{t}-\bar{Y}\right)$ vs $\sum_{t=0}^{\infty} \beta^{t}\left(Y_{t}^{P F}-\bar{Y}\right)$


## Results (1) - Uncertainty and Amplification

Figure 3: IRF - HANK - No ZLB


## Results (2) - Uncertainty and Amplification

Figure 4: IRF - HANK - with ZLB


- AU vs PF in HANK at the ZLB
- certainty equivalence broken

■ $\mathbb{E}_{0} Y_{t}<Y_{t}^{P F}$
■ amplification in PDV: 2x

- Uncertainty: ZLB binds for longer
- On average, 10 quarters
- vs. 4 quarters in PF


## Results (3) - Uncertainty and Amplification in RANK

Figure 5: IRF - RANK - without ZLB


- AU vs PF in RANK at the ZLB
- Calibrate shocks such that:
- RA economy exhibits same response as HANK w/o ZLB (Werning, 2015)

$$
\begin{aligned}
X_{t}(\text { RANK }) & =X_{t}(\text { HANK }) \\
X_{t}^{\tau}(\text { RANK }) & =X_{t}^{\tau}(\text { HANK })
\end{aligned}
$$

## Results (3) - Uncertainty and Amplification in RANK

Figure 5: IRF - RANK - with ZLB


- AU vs PF in RANK at the ZLB
- Calibrate shocks such that:
- RA economy exhibits same response as HANK w/o ZLB (Werning, 2015)

$$
\begin{aligned}
X_{t}(\text { RANK }) & =X_{t}(\text { HANK }) \\
X_{t}^{\tau}(\text { RANK }) & =X_{t}^{\tau}(\text { HANK })
\end{aligned}
$$

- Introduce ZLB


## Results (3) - Uncertainty and Amplification in RANK

Figure 5: IRF - RANK - with ZLB


- AU vs PF in RANK at the ZLB
- Calibrate shocks such that:
- RA economy exhibits same response as HANK w/o ZLB (Werning, 2015)

$$
\begin{aligned}
X_{t}(\text { RANK }) & =X_{t}(\text { HANK }) \\
X_{t}^{\tau}(\text { RANK }) & =X_{t}^{\tau}(\text { HANK })
\end{aligned}
$$

- Introduce ZLB
- Amplification in PDV: 1.6x


## Results (4) - Uncertainty and Amplification - Summary (Y)




|  | No ZLB |  | ZLB |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Perf. Fores. | Agg. Unc. | Perf. Fores. | Agg. Unc. |  |
| Repr. Agent | A | A | B | C | C-B |
| Het. Agents | A | A | D | E | E-D |

## Results (4) - Uncertainty and Amplification - Summary (Y)




|  | No ZLB |  |  | ZLB |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Perf. Fores. | Agg. Unc. |  | Perf. Fores. | Agg. Unc. |  |
| Repr. Agent | 100 | 100 |  | 102.3 | 166.7 | 64.4 |
| Het. Agents | 100 | 100 |  | 104.5 | 225 | 120.5 |

## Results (5) - Computing Time

## Table 2: Running Times - Seconds

| Specification | Benchmark |  | MNP |  |
| :--- | :---: | :---: | :---: | :---: |
| Step | Time | Max. Err. | Time | Max. Err. |
| Steady State | 0.7 | - | 6 | - |
| All Jacobians | 4 | - | 179 | - |
| Algorithm 1 - First-Order | 20 | $0.5 \%$ | 144 | $0.5 \%$ |
| Algorithm 1 - Exact only on TS | 26 | $0.008 \%$ | 216 | $0.002 \%$ |
| Algorithm 1 - Exact Equilibrium | 116 | $0.00000006 \%$ | 7735 | $0.00000002 \%$ |

- Matlab, ASUS laptop, 1.80 Ghz processor, 16GB RAM, and 8 cores
- MNP: Mendicino et al. (2021), richer income risk


## Results (6) - Shock Size

Figure 6: Effects on Impact as a function of shock size



## Results (7) - Decomposition of Consumption Demand

- Define a consumption function:

$$
\begin{align*}
\mathbb{C}^{P F} & =\mathcal{C}^{P F}\left(\mathbb{X}^{P F}, \mathbb{Z}^{P F}\right)  \tag{7}\\
\mathbb{C}^{T S} & =\mathcal{C}^{A U}\left(\mathbb{X}^{T S}, \mathbb{Z}^{T S},\left\{\mathbb{X}^{\tau}\right\}_{\tau=1}^{\tau^{\max }},\left\{\mathbb{Z}^{\tau}\right\}_{\tau=1}^{\tau^{\max }}\right)  \tag{8}\\
\mathbb{C}^{\text {Interm }} & =\mathcal{C}^{P F}\left(\operatorname{IRF}\left(\mathbb{X}^{T S}, \mathbb{Z}^{T S},\left\{\mathbb{X}^{\tau}\right\}_{\tau=1}^{\tau^{\max }},\left\{\mathbb{Z}^{\tau}\right\}_{\tau=1}^{\tau^{\max }}\right)\right) \tag{9}
\end{align*}
$$

- Which aggregate is driving the amplification? $Y, \Pi, R, t, \beta$
- Is uncertainty important per se? Feed IRF of AU in a deterministic world (captures indirect effect via "average" aggregates).


## Results (8) - Decomposition of Consumption Demand

Figure 7: Decomposition of discounted IRF - Consumption


- What price is driving the amplification?
- Feed average prices of AU, in a deterministic world
- Aggregate income is largest driver.
- Expected aggregate income does most of it.


## Other Applications (1) - Forward Guidance

- One policy application: forward guidance
- Central bank announces to keep rates at ZLB for $q$ quarters on top of what prescribed in main exercise
- FG powerful when there is uncertainty (6 quarters can revert recession)



## Application (2) - Two Asset HANK

1. Households

- illiquid physical capital
- Calvo fairy for portfolio re-balancing
$\Rightarrow$ heterogeneous in income, wealth, and portfolio composition

2. Other Blocks

- intermediate-goods producer - Cobb-Douglas production
- Labor Union with adjustment costs (Wage Phillips Curve)
- Capital production subject to adjustment cost


## Application (2.1) - Cyclical Income Risk

## Deterministic Shock

## Stochastic Shock






## Application (2.2) - Earnings Risk

Earnings risk as in Mendicino et al. (2021):


## Conclusions

- We study the interaction b/w aggregate uncertainty and household heterogeneity:
- new methodology for HANK models with aggregate uncertainty and non-linearities
- simulations suggest that interaction is strong at the ZLB, even with acyclical risk
- quantify the interaction in a simple way, during GR ( $55 \%$ amplification)
- Applications:
- Forward Guidance
- Two Asset HANK
- Methodology can be used for many applications involving HA, AU, aggregate non-linearities


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## Results (5) - Uncertainty and Amplification - Summary (П)




|  | No ZLB |  |  | ZLB $(y / P i)$ |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Perf. Fores. | Agg. Unc. |  | Perf. Fores. | Agg. Unc. |
| Repr. Agent | 100 | 100 |  | 100.45 | 167.3 |
| Het. Agents | 100 | 100 |  | 101.9 | 227 |

## Solution Approach (3) - Heterogeneous Agents Block

- Similar to Sequence-Space Jacobian. Heterogeneous block is represented by:

$$
\begin{align*}
\mathbf{v}_{t} & =v^{T S}\left(\mathbf{v}_{t+1}, \mathbf{v}_{t+1}^{t+1}, X_{t}\right)  \tag{10}\\
D_{t+1}^{t+1}=D_{t+1} & =\Lambda^{T S}\left(\mathbf{v}_{t+1}, \mathbf{v}_{t+1}^{t+1}, X_{t}\right)^{\prime} D_{t}  \tag{11}\\
\mathcal{Y}_{t} & =y^{T S}\left(\mathbf{v}_{t+1}, \mathbf{v}_{t+1}^{t+1}, X_{t}\right)^{\prime} D_{t}  \tag{12}\\
\mathbf{v}_{t}^{\tau} & =v\left(\mathbf{v}_{t+1}^{\tau}, X_{t}^{\tau}\right)  \tag{13}\\
D_{t+1}^{\tau} & =\Lambda\left(\mathbf{v}_{t+1}^{\tau}, X_{t}^{\tau}\right)^{\prime} D_{t}^{\tau}  \tag{14}\\
\mathcal{Y}_{t}^{\tau} & =y\left(\mathbf{v}_{t+1}^{\tau}, X_{t}^{\tau}\right)^{\prime} D_{t}^{\tau} \tag{15}
\end{align*}
$$

## Solution Approach (4) - Equilibrium

- A competitive equilibrium is
- Aggregate variables
- a sequence $\left\{Y_{t}, \Pi_{t}, R_{t}, b_{t}, t_{t}\right\}_{t=0}^{\max ^{\text {ma }}-1}=\left\{X_{t}\right\}_{t=0}^{T_{\text {max }}^{\text {max }}-1}=\mathbb{X}^{T S}$
- $\tau^{\text {max }}$ sequences $\left\{\left\{Y_{t}^{\tau}, \Pi_{t}^{\tau}, R_{t}^{\tau}, b_{t}^{\tau}, t_{t}^{\tau}\right\}_{t=\tau}^{\tau+\tau}\right\}_{\tau=1}^{\tau^{\text {max }}}=\left\{\left\{X_{t}^{\tau}\right\}_{t=\tau}^{\tau+\tau}\right\}_{\tau=1}^{\tau^{\max }}=\left\{\mathbb{X}^{\tau}\right\}_{\tau=1}^{\tau^{\max }}$,
- Individual agents objects (wealth distribution, value function)
- a sequence $\left\{D_{t+1}, V_{t}\right\}_{t=0}^{\tau^{\text {max }}-1}$
- $\tau^{\text {max }}$ sequences $\left\{\left\{D_{t}^{\tau}, V_{t}^{\tau}\right\}_{t=\tau}^{\tau+T}\right\}_{\tau=1}^{\tau^{\text {max }}}$
- s.t. given exogenous processes $\left\{\beta_{t}\right\}_{t=0}^{\tau^{\text {max }}}=\mathbb{Z}^{T S}$ and $\left\{\left\{\beta_{t}^{\tau}\right\}_{t=0}^{\tau^{\text {max }}}\right\}_{\tau=1}^{\tau^{\max }}=\left\{\mathbb{Z}^{\tau}\right\}_{\tau=1}^{\tau^{\max }}$, aggregate equations hold, agents solve their maximization problem, and $D_{t}=D_{t}^{t}$


## Solution Approach (6) - Occasionally Binding

- Occasionally binding constraints sub-algorithm

1. Consider $d \mathbb{X}^{T S}=\left(\mathbf{F}_{X}^{T S}\right)^{-1}\left(\mathbf{F}_{\mathbb{Z}}^{T S} d \mathbb{Z}+\mathbf{F}_{\mathbb{X}}^{T S} d \mathbb{X}_{1}^{P F}+\mathbf{F}_{\mathrm{V}}^{T S} d \mathbb{V}_{1}^{P F}\right)$
2. Guess periods in which the constraint binds, place them in an binary vector $I_{\text {ZLB }}$
3. Adjust the main matrix so that

$$
\begin{align*}
d \mathbb{X}^{T S}= & {\left[\left(1-I_{Z L B}\right) \times \mathbf{F}_{X}^{T S}+I_{Z L B} \times \tilde{\mathbf{F}}_{X}^{T S}\right]^{-1} } \\
& {\left[\left(1-I_{Z L B}\right) \times\left(\mathbf{F}_{\mathbb{Z}}^{T S} d \mathbb{Z}+\mathbf{F}_{\mathbb{X}}^{T S} d \mathbb{X}_{1}^{P F}+\mathbf{F}_{V}^{T S} d \mathbb{V}_{1}^{P F}\right)+I_{Z L B} \times(\underline{R}-\bar{R})\right] } \tag{16}
\end{align*}
$$

where $\tilde{\mathbf{F}}_{X}^{T S}$ substitutes the Taylor rule with $R_{t}=\underline{R}$

- Generate shadow rates by simply multiplying $d \mathbb{X}^{T S}$ and $\mathbf{F}_{X}^{T S}$, is the guess is correct, stop. Otherwise go to 2 and update $I_{Z L B}$.


## Solution Approach (7) - Others

## Solution Approach (7) - Others

- We exploit:

■ fake news algorithm
■ expectations vector

## Solution Approach (7) - Others

- We exploit:
- fake news algorithm
- expectations vector
- We do not exploit:
- DAG-part


## Solution Approach (7) - Others

- We exploit:
- fake news algorithm
- expectations vector
- We do not exploit:
- DAG-part
- New Jacobian $\frac{\partial A_{t}}{\partial Y_{s}}$ :
- different $\mu$



## Results (6) - Shock Size

Figure 8: Effects on Discounted IRF as a function of shock size


