

Anchored Inflation Expectations and the Slope of the Phillips Curve¹

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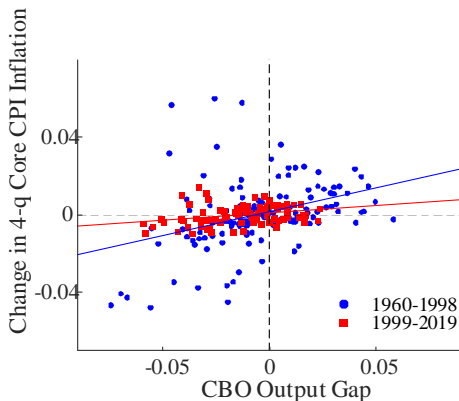
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The “flattening” of the Phillips Curve

“The relationship between slack in the economy...and inflation was a strong one 50 years ago...and that has gone away”

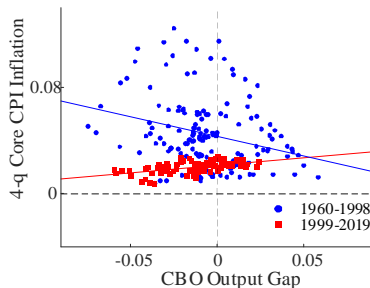
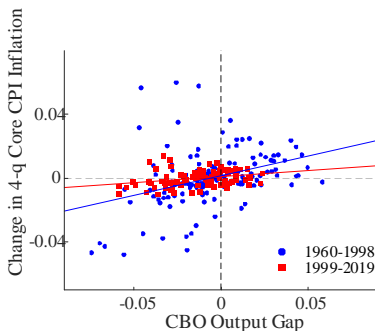
Fed Chair Jerome Powell July 11, 2019.



Has the Phillips Curve become “flatter”?

- Depends on what we mean by “the Phillips Curve”

- NKPC: $\pi_t = \tilde{E}_t \pi_{t+1} + \kappa y_t + u_t$
- Left panel: $\pi_t = \pi_{t-1} + \kappa y_t + u_t$ (backward-looking)
- Right panel: $\pi_t = \bar{\pi} + \kappa y_t + u_t$ (“original”)



Key moments of US inflation data

Moments of U.S. inflation

	1960.q1-1998.q4	1999.q1-2019.q2	1999.q1-2007.q3
$Corr(\pi_t, y_t)$	-0.10	0.36	0.28
$Corr(\Delta\pi_t, y_t)$	0.14	0.03	0.07
$Corr(\pi_t, \pi_{t-1})$	0.75	0.20	0.20
$Std.Dev(4\pi_t)$	2.91	0.80	0.77

Note: π_t is quarterly core CPI inflation and y_t is the CBO output gap

- $Corr(\Delta\pi_t, y_t) \downarrow$ but $Corr(\pi_t, y_t) \uparrow$
 - similar results for alternative measures of inflation or alternative gap variables

Theories of the “flatter” Phillips Curve

- New Keynesian Phillips Curve (NKPC):

$$\pi_t = \tilde{E}_t \pi_{t+1} + \kappa y_t + u_t, \quad u_t \sim N(0, \sigma_u^2),$$

- 1 **The PC has become structurally flatter** $\Rightarrow \kappa \downarrow$
(Ball & Mazumder 2011; IMF 2013; Blanchard, et al. 2015)
- 2 **Monetary policy has blurred the statistical correlation between π_t and $y_t \Rightarrow \text{Corr}(y_t, u_t) < 0$**
(Bullard 2018; McLeay & Tenreiro 2020)

All else equal, #1 and #2 imply $\text{Corr}(\pi_t, y_t) \downarrow$
 \Rightarrow but the opposite has happened in the data!

Alternative theory:

- 3 **Inflation expectations have become more firmly anchored**
(Mishkin 2007; Bernanke 2007, 2010; Stock 2011; Blanchard 2016; Hazell et. al. 2020)

This paper

- We estimate a NKPC on US data that allows for changes in the degree of anchoring of expected inflation
 - ① Expectations have become much better anchored over the Great Moderation
 - ② The structural slope coefficient κ has been stable since 1960
 - ③ There is no “missing disinflation” puzzle or “missing inflation” puzzle
- In a simple New Keynesian model with endogenous anchoring:
 - ① An increase in the Taylor rule coefficient on inflation serves to endogenously anchor agents' subjective inflation expectations
 - ② Improved anchoring implies $Corr(\Delta\pi_t, y_t) \downarrow$ but $Corr(\pi_t, y_t) \uparrow$
 - ③ It also implies $Std.Dev(\pi_t) \downarrow$ and $Corr(\pi_t, \pi_{t-1}) \downarrow$

Formalizing anchoring

- Motivated by survey evidence (Coibion & Gorodnichenko 2015), we postulate:

$$\tilde{E}_t \pi_{t+1} = \tilde{E}_{t-1} \pi_t + \lambda_\pi (\pi_t - \tilde{E}_{t-1} \pi_t),$$

where λ_π = gain parameter

- λ_π is an inverse measure of the degree of anchoring
 - *“I use the term ‘anchored’ to mean relatively insensitive to incoming data”* – Bernanke (2007)
- Optimal forecast rule if agents employ an unobserved components time series model to forecast inflation along the lines of Stock & Watson (2007, 2010)
 - A “signal extraction” forecast rule

NKPC estimation: Has the structural slope declined?

- Substitute forecast rule into NKPC and solve for π_t :

$$\pi_t = \tilde{E}_{t-1}\pi_t + \frac{\kappa}{1 - \lambda_\pi}y_t + \frac{1}{1 - \lambda_\pi}u_t,$$

where $\tilde{E}_{t-1}\pi_t = \tilde{E}_{t-2}\pi_{t-1} + \lambda_\pi(\pi_{t-1} - \tilde{E}_{t-2}\pi_{t-1})$

- Estimate κ and λ_π
 - Generalized IV using lagged variables as instruments (Gali & Gertler 1999)
 - Using data for core CPI inflation and the CBO output gap from 1960.q1 to 2019.q2.
 - Including current and lagged oil price inflation as regressors
 - Instruments: Two lags of core CPI inflation and oil price inflation and one lag of the CBO output gap and wage inflation
- Split data into three subsamples.

NKPC estimation: Results (1/2)

Three “Great” Eras

	Great Inflation 1960.q1 to 1983.q4	Great Moderation 1984.q1 to 2007.q3	Great Recession 2007.q4 to 2019.q2
A. Signal-extraction: $\tilde{E}_t \pi_{t+1} = \tilde{E}_{t-1} \pi_t + \lambda_\pi (\pi_t - \tilde{E}_{t-1} \pi_t)$			
$\hat{\kappa}$	0.066*** (0.115)	0.042*** (0.015)	0.063*** (0.013)
$\hat{\lambda}_\pi$	0.280*** (0.021)	0.119** (0.059)	0.008 (0.010)

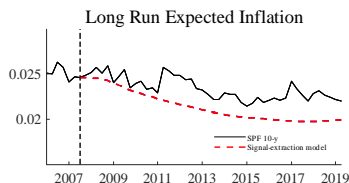
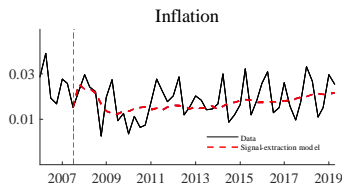
Notes: The asterisks ***, ** and * denote significance at the 1, 5, and 10% levels, respectively. The estimation uses quarterly inflation rates (not annualized). Newey-West standard errors are shown in parentheses

NKPC estimation: Results (2/2)

	Great Inflation 1960.q1 to 1983.q4	Great Moderation 1984.q1 to 2007.q3	Great Recession 2007.q4 to 2019.q2
B. Survey Data: $\tilde{E}_t \pi_{t+1} = \tilde{E}_t^s \pi_{t+h}$			
	1-q SPF		
$\hat{\kappa}$		0.006 (0.020)	0.026** (0.011)
	5-y MSC		
$\hat{\kappa}$		0.024** (0.011)	0.070*** (0.015)
	10-y SPF		
$\hat{\kappa}$		0.041*** (0.010)	0.065*** (0.019)

Resolving the inflation puzzles

- Estimate model on 1999.q1-2007.q3 subsample.
 - $\hat{\lambda}_{\pi} = 0.024, \hat{\kappa} = 0.048^{***}$
- Out-of-sample forecast: Compute (median) projected paths for π_t and $\tilde{E}_t \pi_{t+1}$ from 2007.q4 to 2019.q2, conditional on $y_t = \text{CBO output gap}$.



- No “missing disinflation” during Great Recession.
- No “missing inflation” during subsequent recovery.

Endogenous anchoring in New Keynesian model (1/4)

- How does a shift towards a more hawkish monetary policy affect
 - ① the degree of anchoring, i.e. λ_π ?
 - ② the slopes of the backward-looking PC and the original PC, respectively?
- Counterfactual implication of RE: $Corr(\pi_t, y_t) \downarrow$
(Bullard 2018; McLeay and Tenreyro 2020)
- We show that an endogenous anchoring mechanism can overturn this counterfactual prediction

Endogenous anchoring in New Keynesian model (2/4)

Phillips curve:

$$\pi_t = \beta \tilde{E}_t \pi_{t+1} + \kappa y_t + u_t, \quad u_t \sim N(0, \sigma_u^2).$$

IS curve:

$$y_t = \tilde{E}_t y_{t+1} - \alpha(i_t - \tilde{E}_t \pi_{t+1}) + v_t, \quad v_t \sim N(0, \sigma_v^2),$$

Taylor-type policy rule:

$$i_t = \mu_\pi \tilde{E}_t \pi_{t+1} + \mu_y \tilde{E}_t y_{t+1},$$

Subjective forecast rules:

$$\begin{aligned} \tilde{E}_t \pi_{t+1} &= \tilde{E}_{t-1} \pi_t + \lambda_\pi (\pi_t - \tilde{E}_{t-1} \pi_t), \\ \tilde{E}_t y_{t+1} &= \tilde{E}_{t-1} y_t + \lambda_y (y_t - \tilde{E}_{t-1} y_t). \end{aligned}$$

How does anchoring affect the original PC slope?

- Consider simplified model with $\lambda_y \rightarrow 0$ and $\tilde{E}_{t-2}\pi_{t-1} \simeq 0$.
Implies:

$$\begin{aligned} \text{Cov}(\pi_t, y_t) \simeq & - \frac{\alpha(\mu_\pi - 1)\hat{\beta}(1 - \lambda_\pi)^2 \lambda_\pi^2}{(1 - \hat{\beta}\lambda_\pi)^2} \text{Var}(\pi_{t-1}) \\ & + \frac{(1 - \beta\lambda_\pi)\kappa}{(1 - \hat{\beta}\lambda_\pi)^2} \sigma_v - \frac{\alpha(\mu_\pi - 1)\lambda_\pi}{(1 - \hat{\beta}\lambda_\pi)^2} \sigma_u, \end{aligned}$$

where $\hat{\beta} = \beta - \kappa\alpha(\mu_\pi - 1)$.

- 1 Lagged inflation π_{t-1} induces **negative** co-movement
- 2 Demand shocks v_t induce **positive** co-movement.
- 3 Cost-push shocks u_t induce **negative** co-movement

For $\lambda_\pi \rightarrow 0$, first and third terms go to zero and $\frac{\text{Cov}(\pi_t, y_t)}{\text{Var}(y_t)} \rightarrow \kappa$

Can anchoring explain the shifting relative slopes?

- Yes. Note the following definitional relationship:

$$\frac{\text{Cov}(\Delta\pi_t, y_t)}{\text{Var}(y_t)} - \frac{\text{Cov}(\pi_t, y_t)}{\text{Var}(y_t)} = - \frac{\text{Cov}(\pi_{t-1}, y_t)}{\text{Var}(y_t)}$$

- Poor anchoring implies $\text{Cov}(\pi_{t-1}, y_t) < 0$
 \Rightarrow backward-looking slope exceeds original slope
 - Intuition: $\pi_{t-1} \uparrow \Rightarrow \tilde{E}_t \pi_{t+1} \uparrow \Rightarrow \pi_t \uparrow \Rightarrow i_t \uparrow \Rightarrow y_t \downarrow$
- Improved anchoring, i.e. $\lambda_\pi \downarrow$, *weakens* this negative co-movement force
 - This will serve to “flatten” the backward-looking PC relative to the original PC
 - Indeed, in US data, $\text{Cov}(\pi_{t-1}, y_t)$ has gone from negative to positive

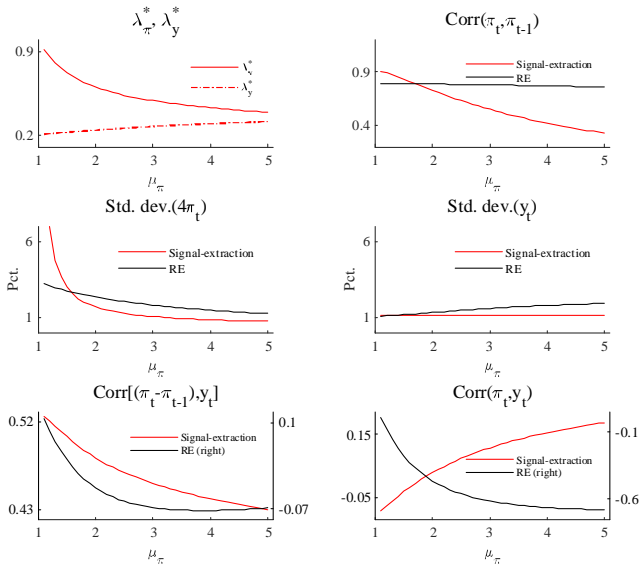
Unique fixed point learning equilibrium

- All else equal, $\mu_\pi \uparrow \Rightarrow \text{Corr}(\pi_t, y_t) \downarrow$
- Introduce *endogenous* anchoring mechanism
- Unique fixed point learning equilibrium:
 - Agents use unobserved components models to forecast inflation and the output gap
 \Rightarrow signal-extraction forecast rules are perceived optimal!
 - λ_π^* is endogenously (and uniquely) pinned down by the statistic $\text{Corr}(\Delta\pi_t, \Delta\pi_{t-1})$
 - Endogenous anchoring mechanism:
 $\mu_\pi \uparrow \Rightarrow \text{Corr}(\Delta\pi_t, \Delta\pi_{t-1}) \downarrow \Rightarrow \lambda_\pi^* \downarrow \Rightarrow \text{Corr}(\pi_t, y_t) \uparrow$

Endogenous anchoring in New Keynesian model (3/4)

- Key question: How will $\mu_\pi \uparrow$ affect $Corr(\Delta\pi_t, y_t)$ and $Corr(\pi_t, y_t)$ with endogenous anchoring?
- Exercise: Compute these moments for different values of the policy rule coefficient μ_π
 - Signal-extraction model vs. RE version of the model (with persistent shocks)
 - Standard calibration (see paper for details)

Endogenous anchoring in New Keynesian model (4/4)



Conclusion

- U.S. inflation expectations have become much better anchored over the Great Moderation period.
- Accounting for improved anchoring, estimated NKPC slope parameter κ is statistically significant and stable from 1960 to 2019.
- Out-of-sample forecasts resolve inflation puzzles.
- In a simple NK model, a stronger Taylor rule response to inflation helps to:
 1. Endogenously anchor $\tilde{E}_t \pi_{t+1}$.
 2. Flatten backward-looking PC.
 3. Resurrect the original PC.
 4. Reduce inflation volatility.
 5. Lower inflation persistence.